

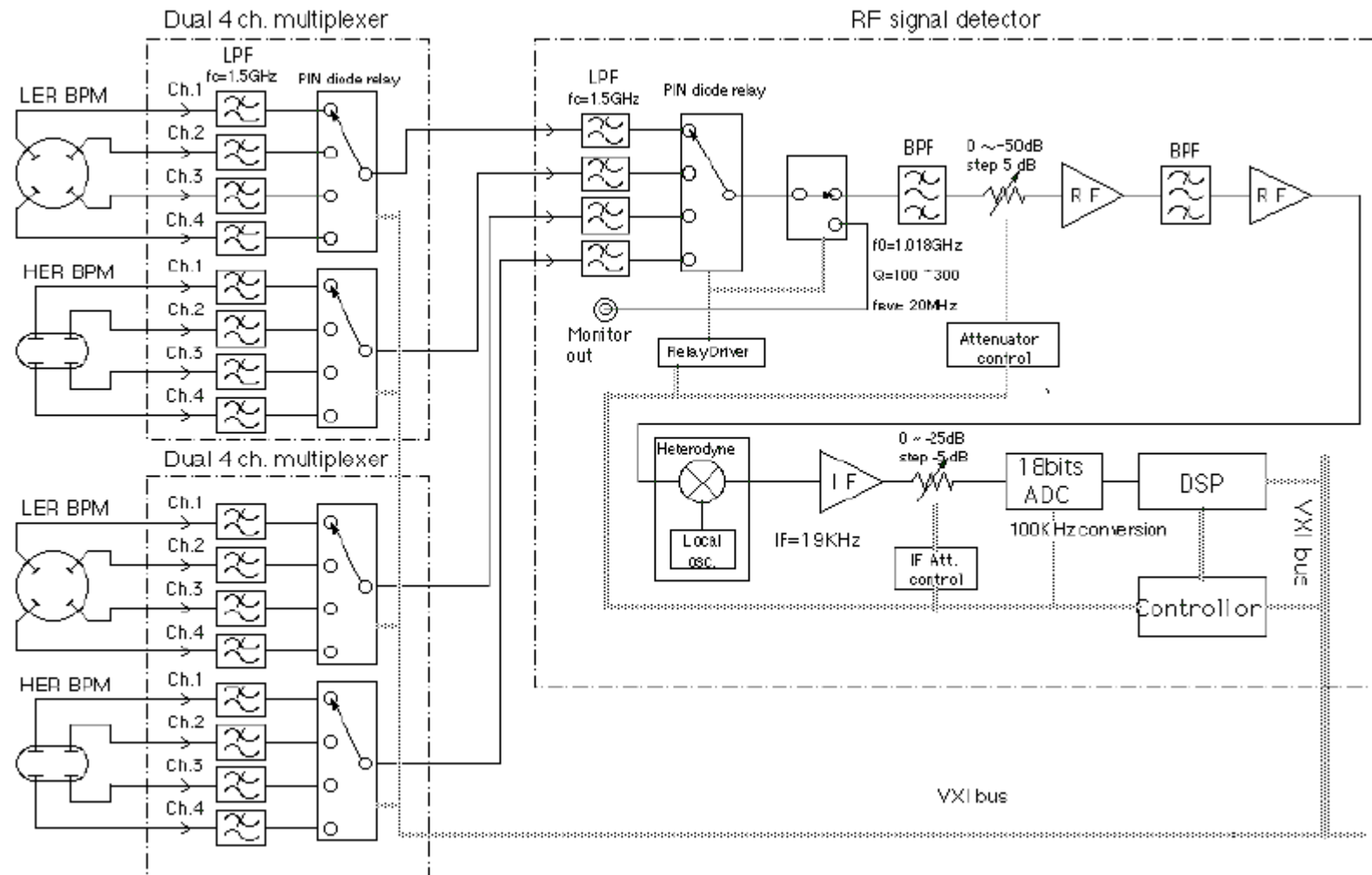


Beam diagnostics, Feedback systems

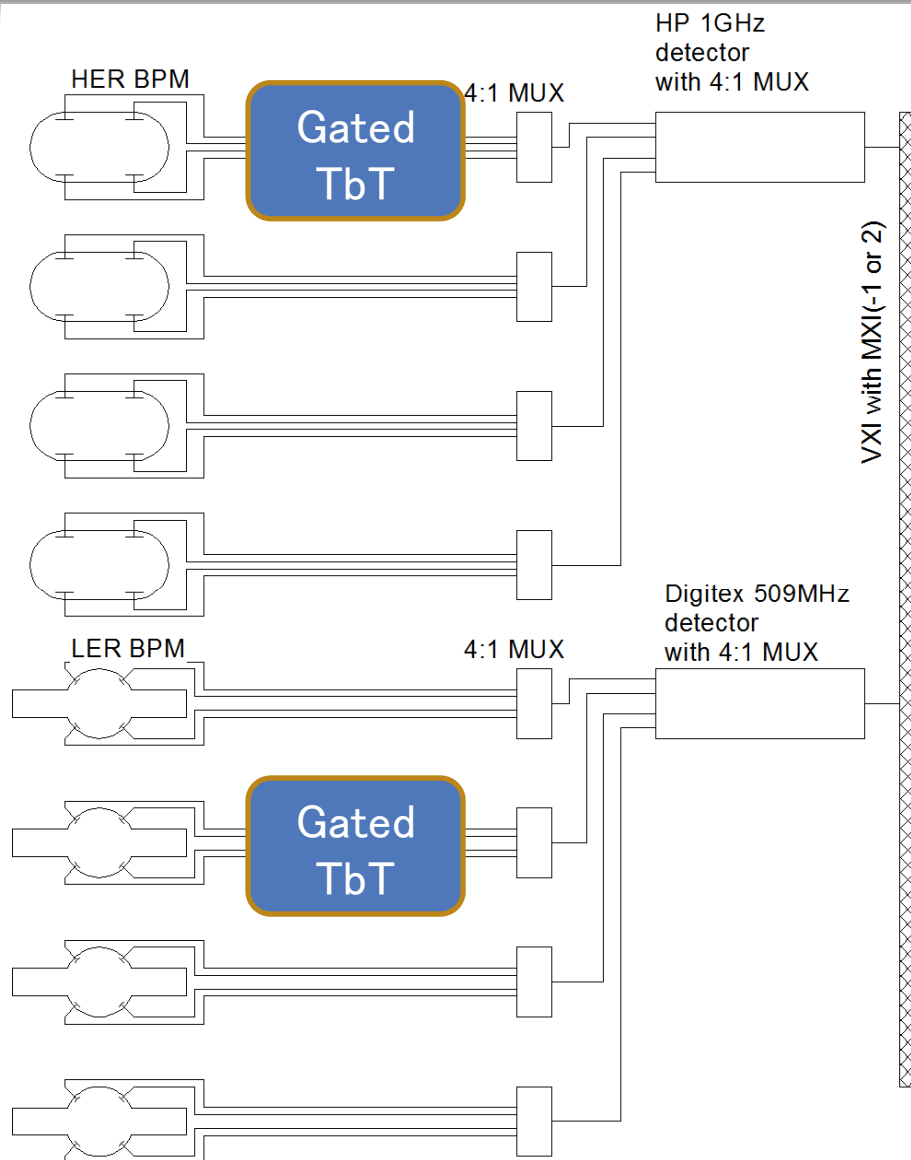
Makoto Tobiyama

KEK Accelerator Laboratory

KEKB COD measurement system

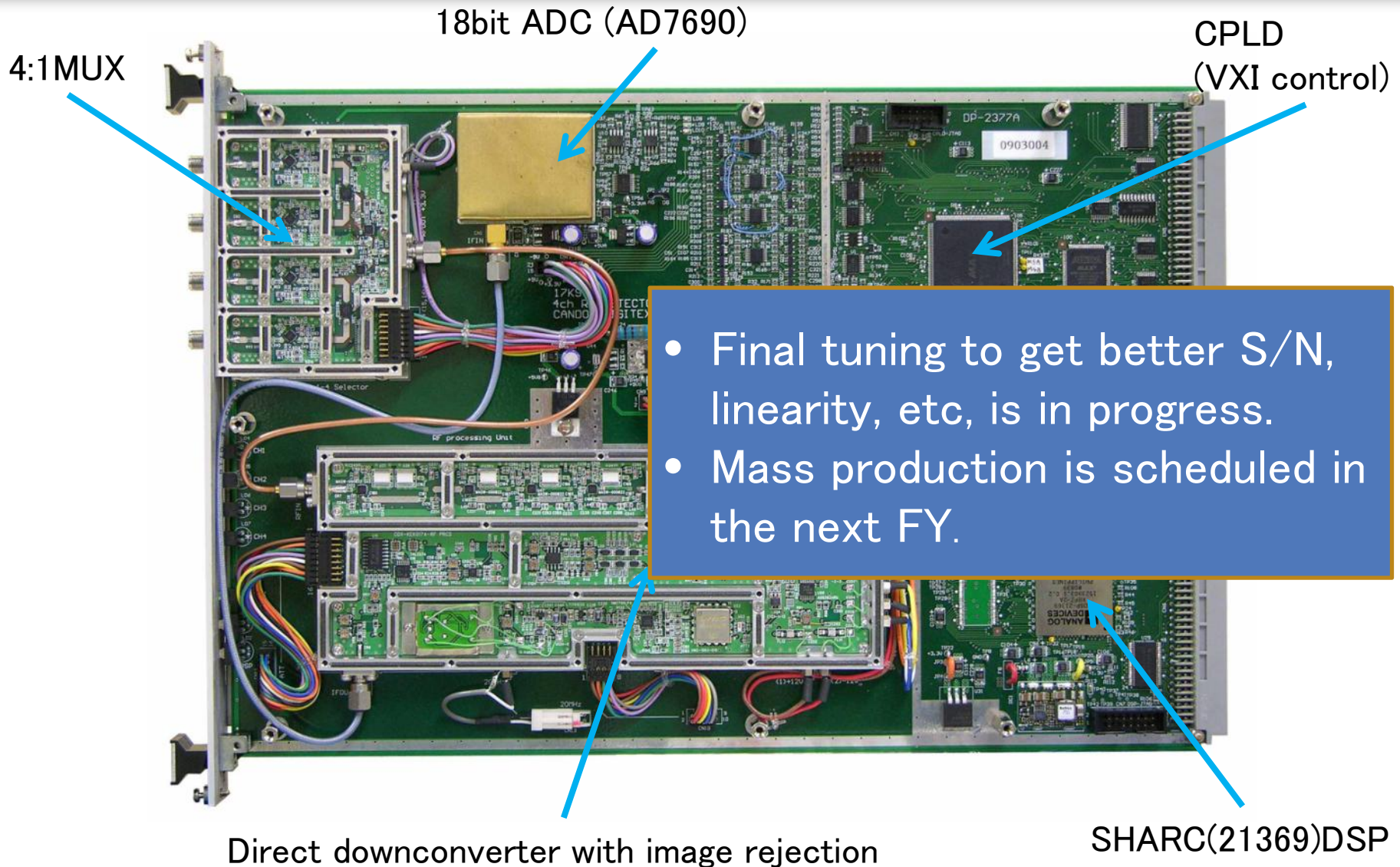


SuperKEKB COD measurement

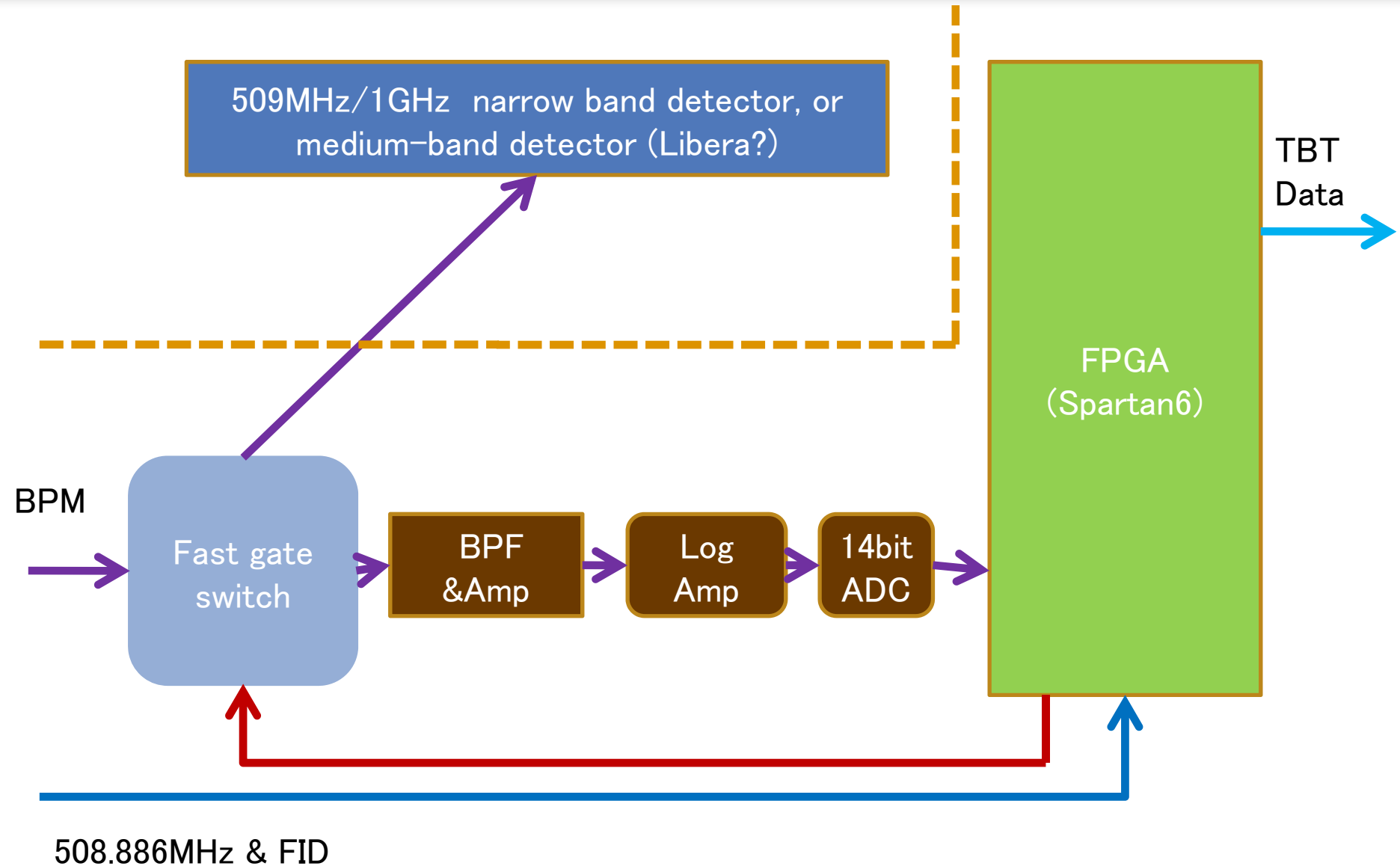


- **Separate HER and LER BPM systems**
 - Cutoff freq. of LER chamber lower than 1GHz.
- **Continue to use VXI system with MXI (1/2) connection.**
- **Selected BPMs have gated turn-by-turn monitor function.**

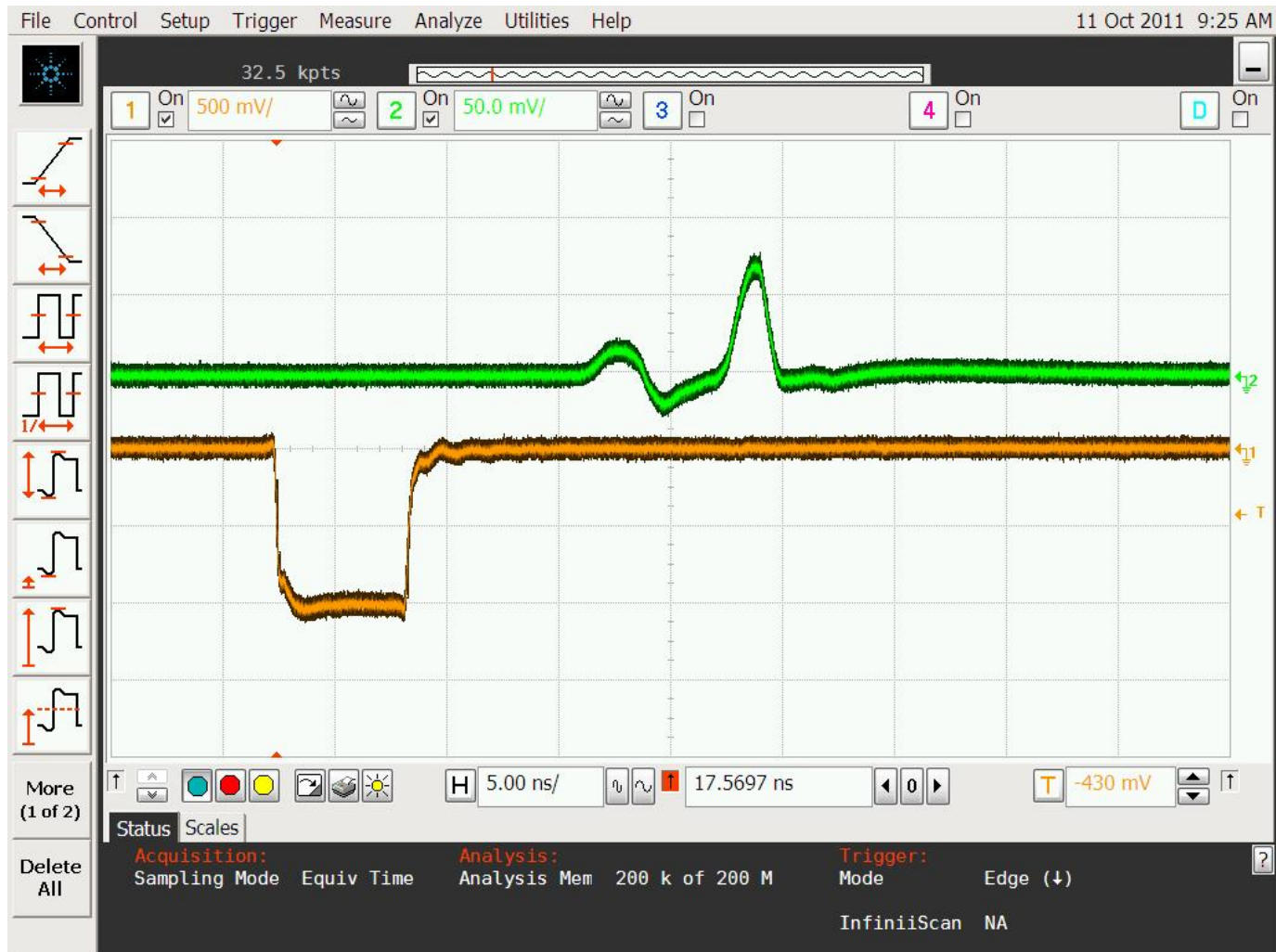
Digitex 17K94A 509MHz detector



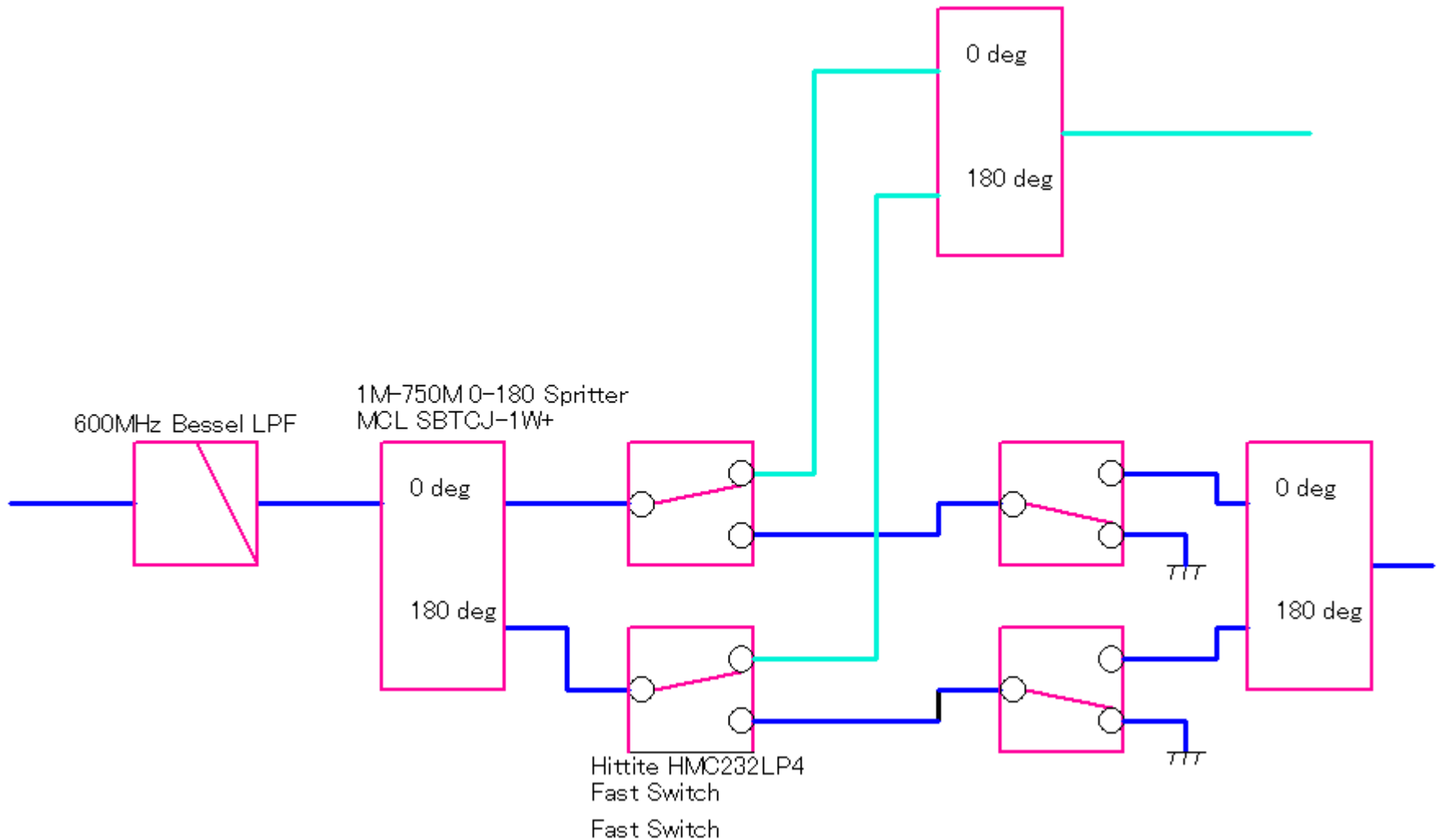
Gated turn-by-turn monitor



Switching noise



Better isolation and switching noise cancellation

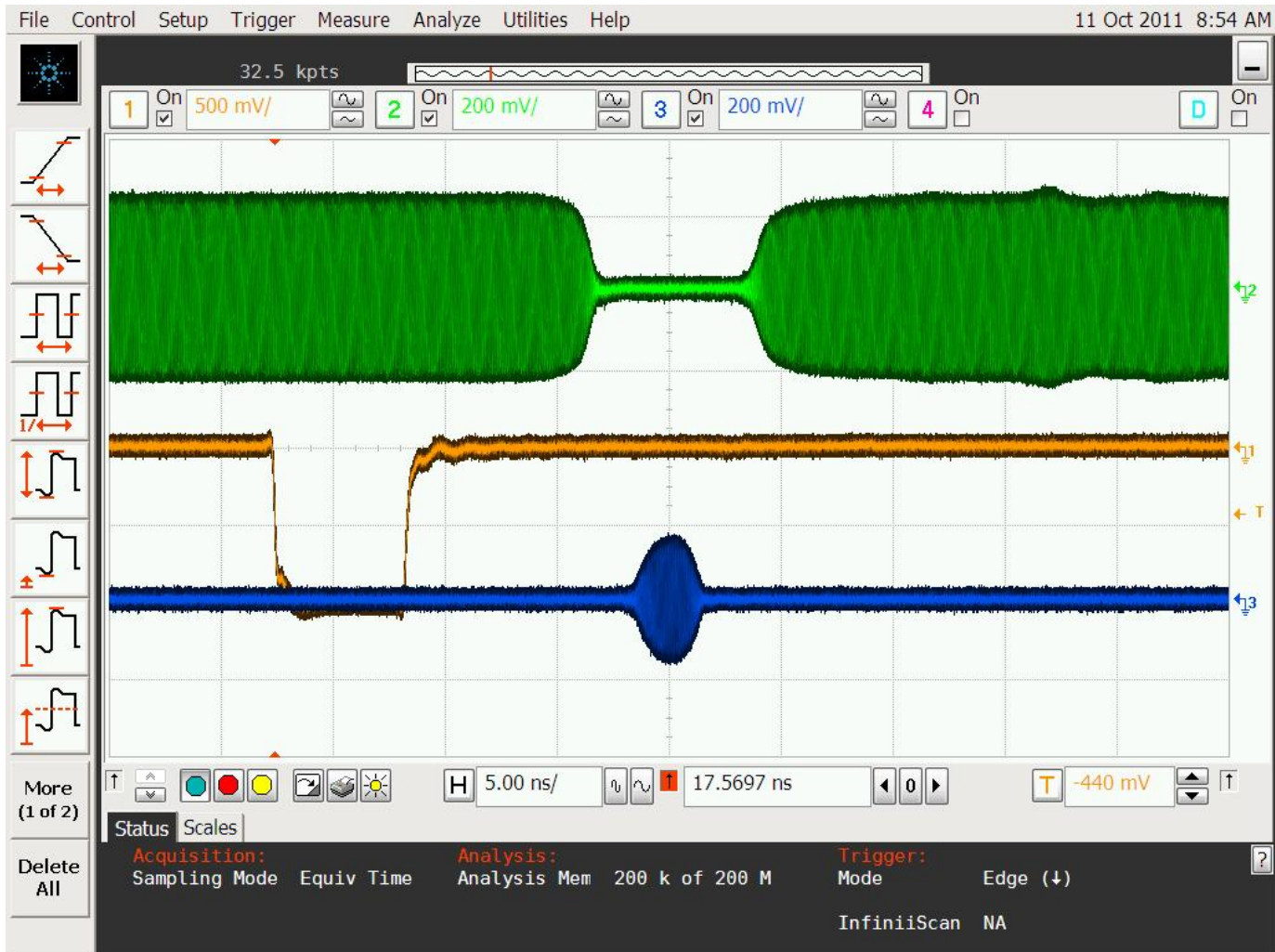


Proposed and tested by Dr. T. Naito

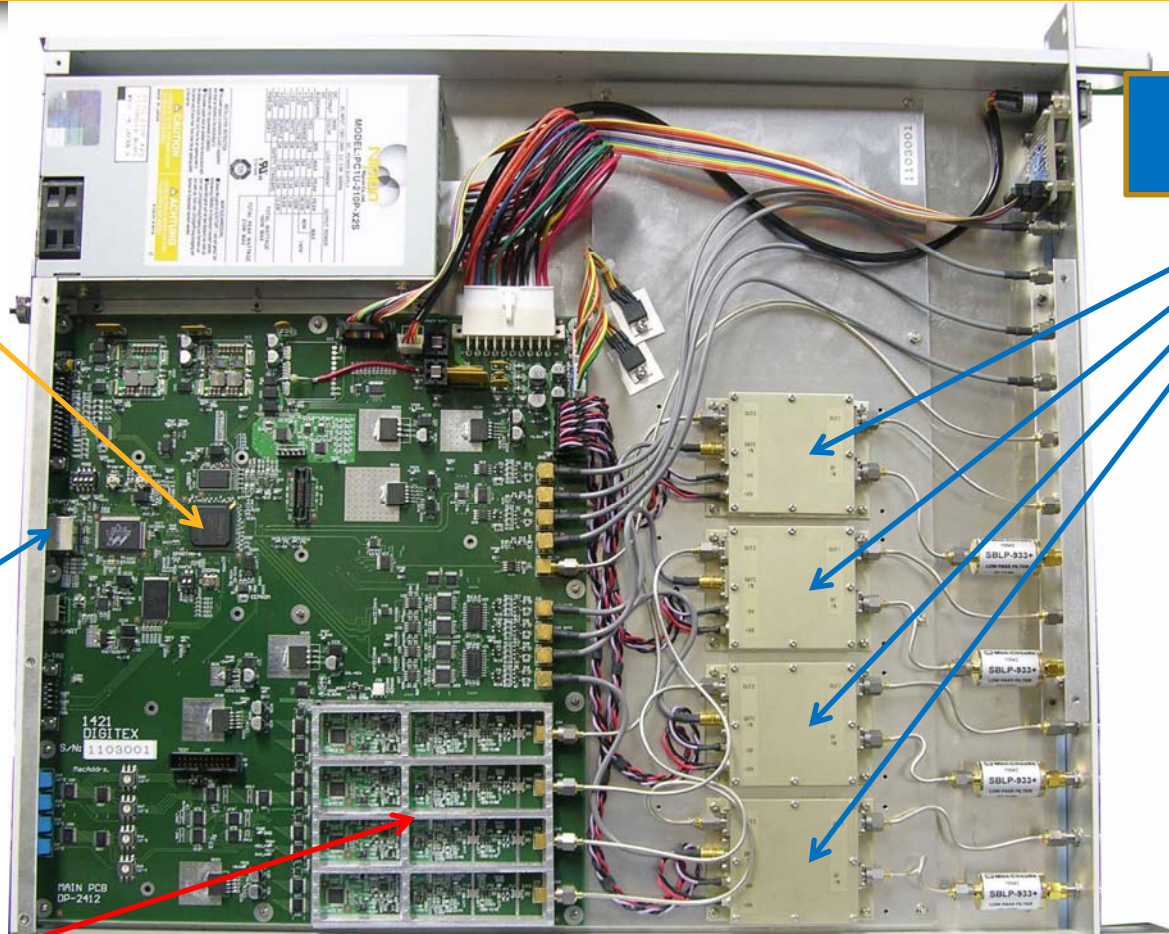
Switching noise



Switching



Board view

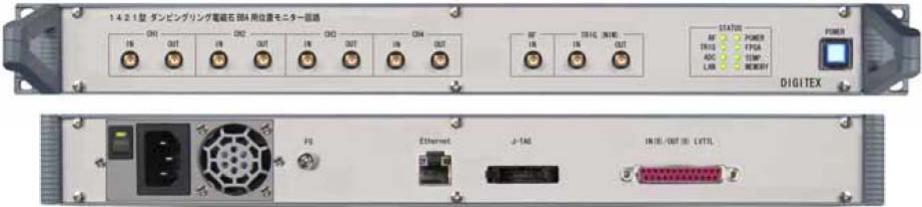


Spartan6LX
100T FPGA

Fast Gate SW

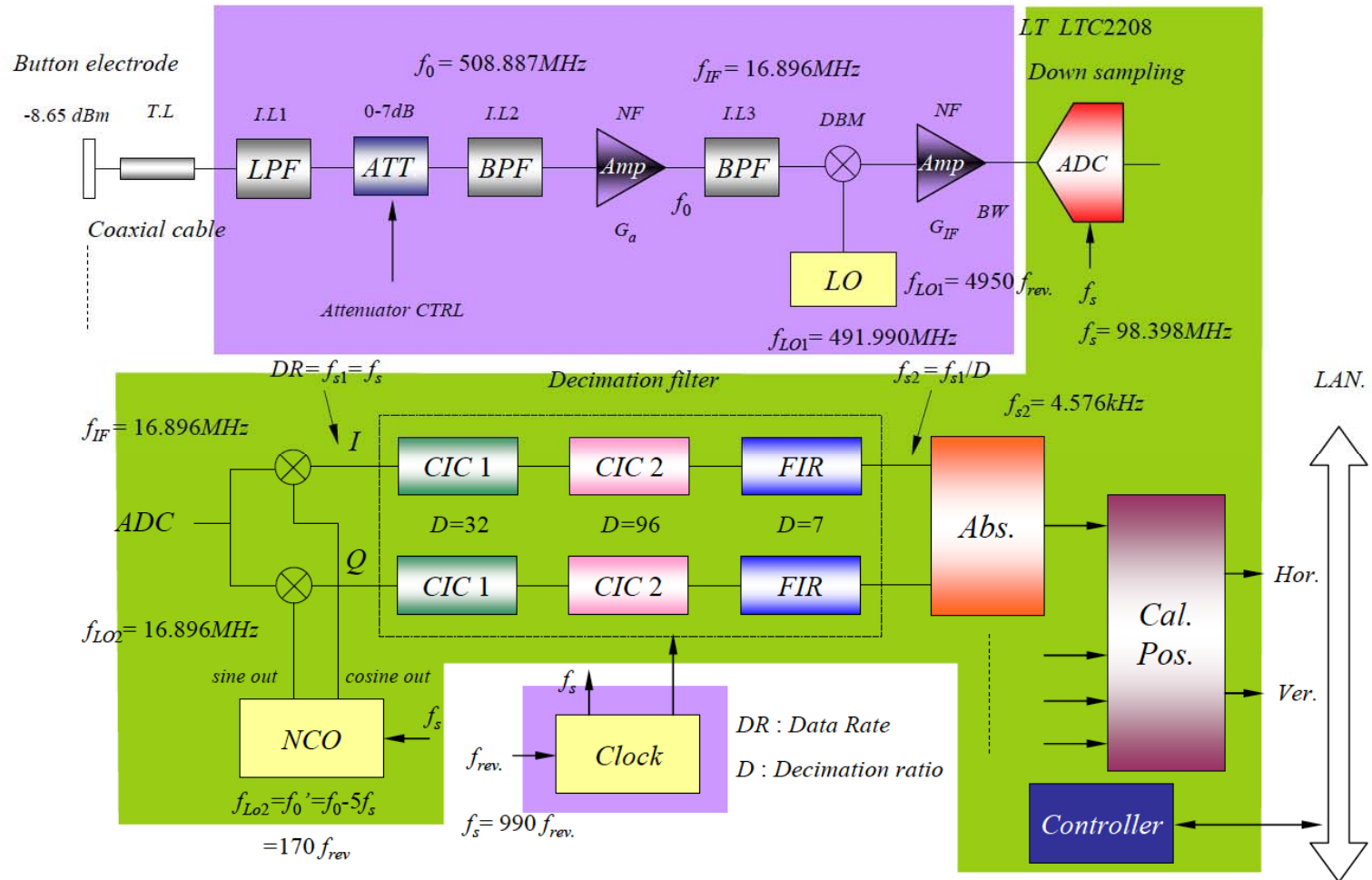
GbE port

Log amp and
14bit ADC

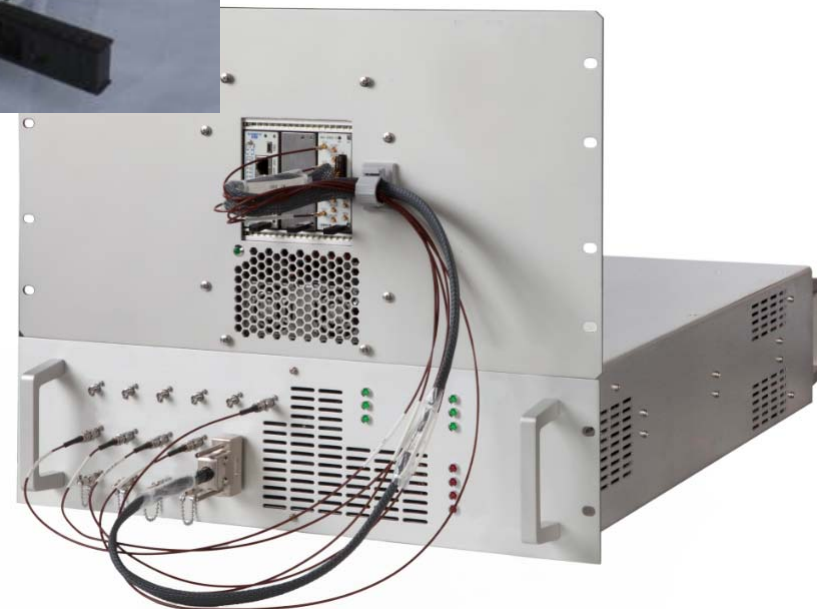


1U size

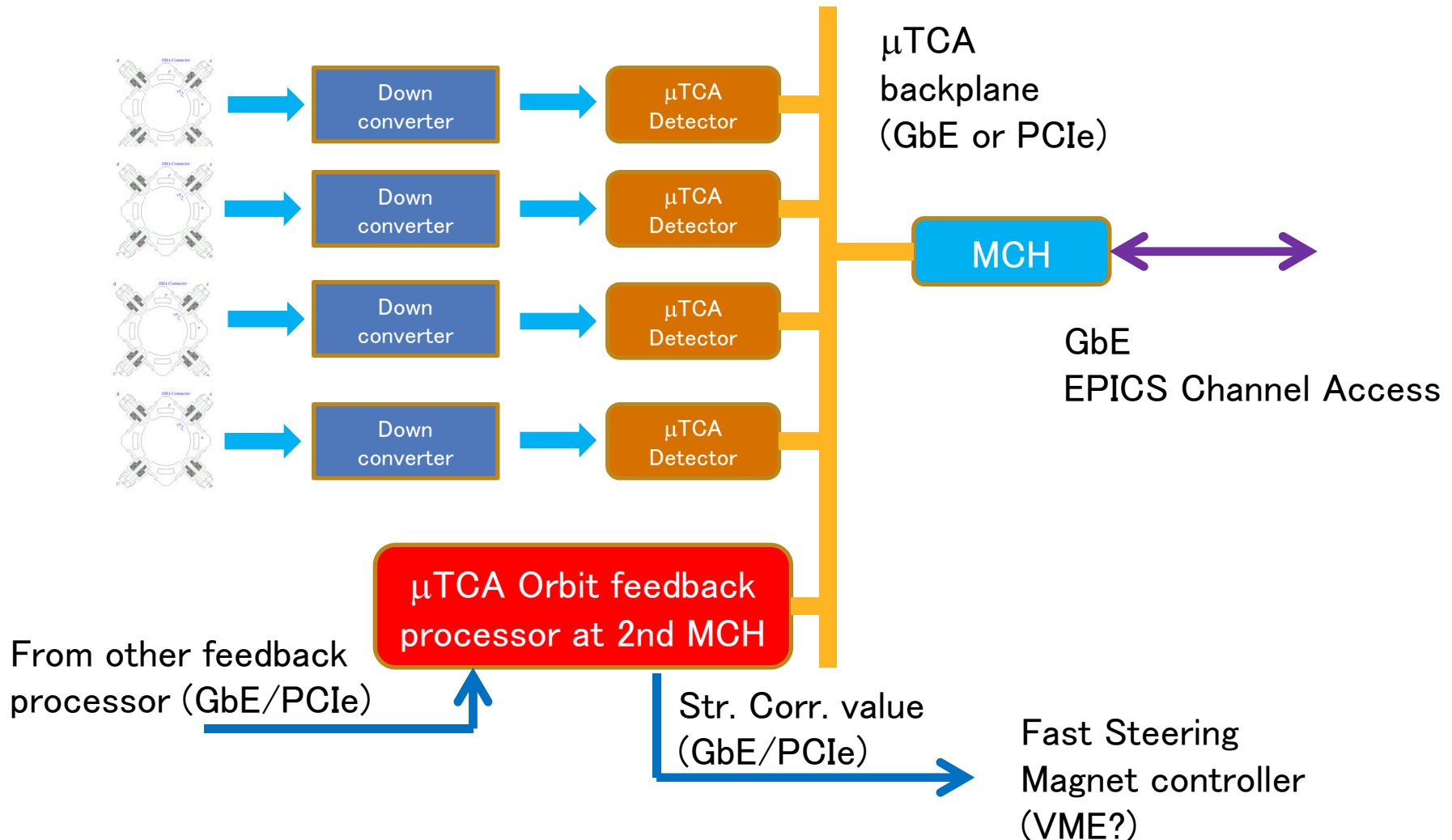
IR feedback detector



μ TCA size board

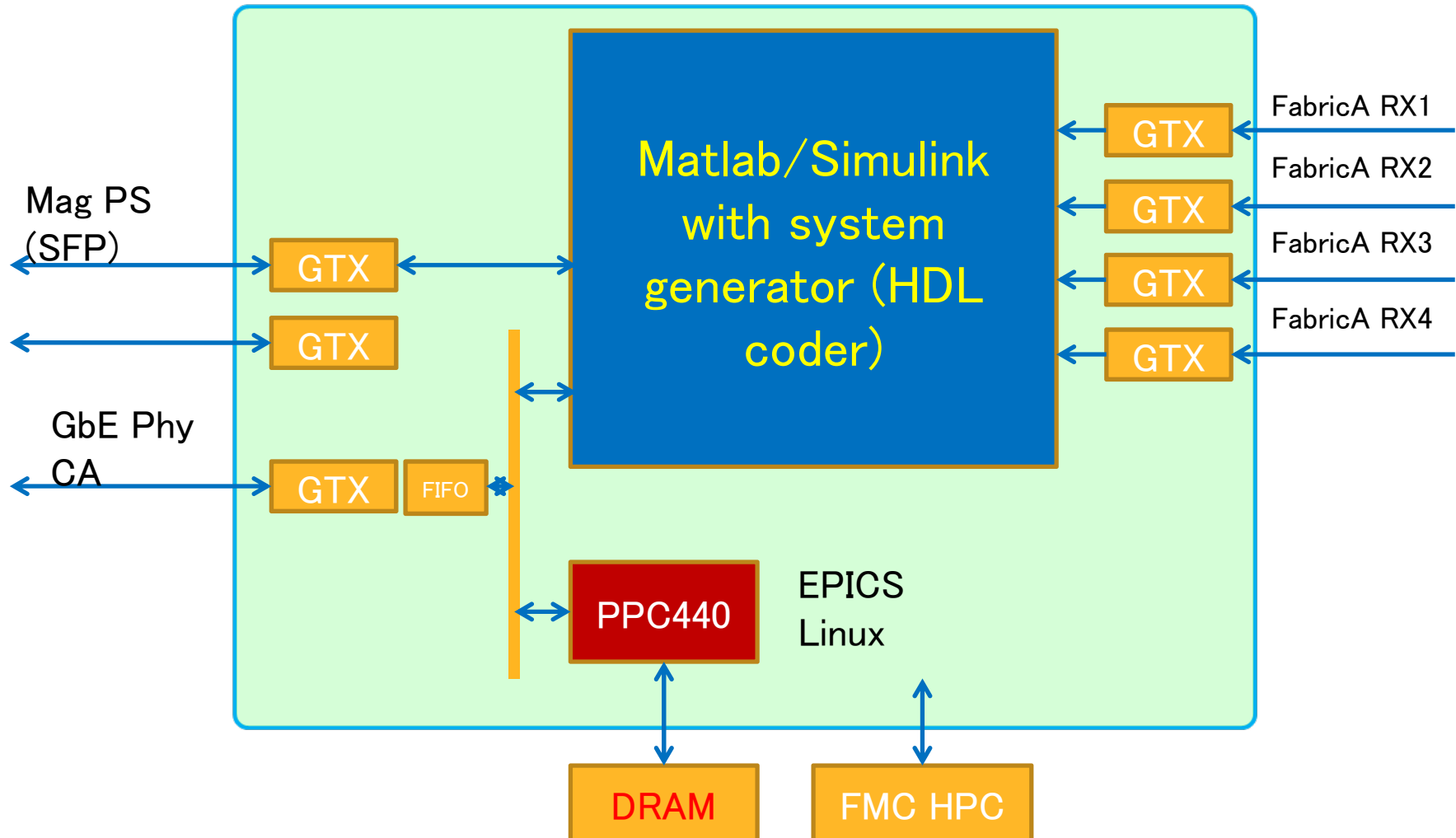


IR orbit feedback



Feedback processor board

Virtex5-XC5FX200T(FF1738) FPGA



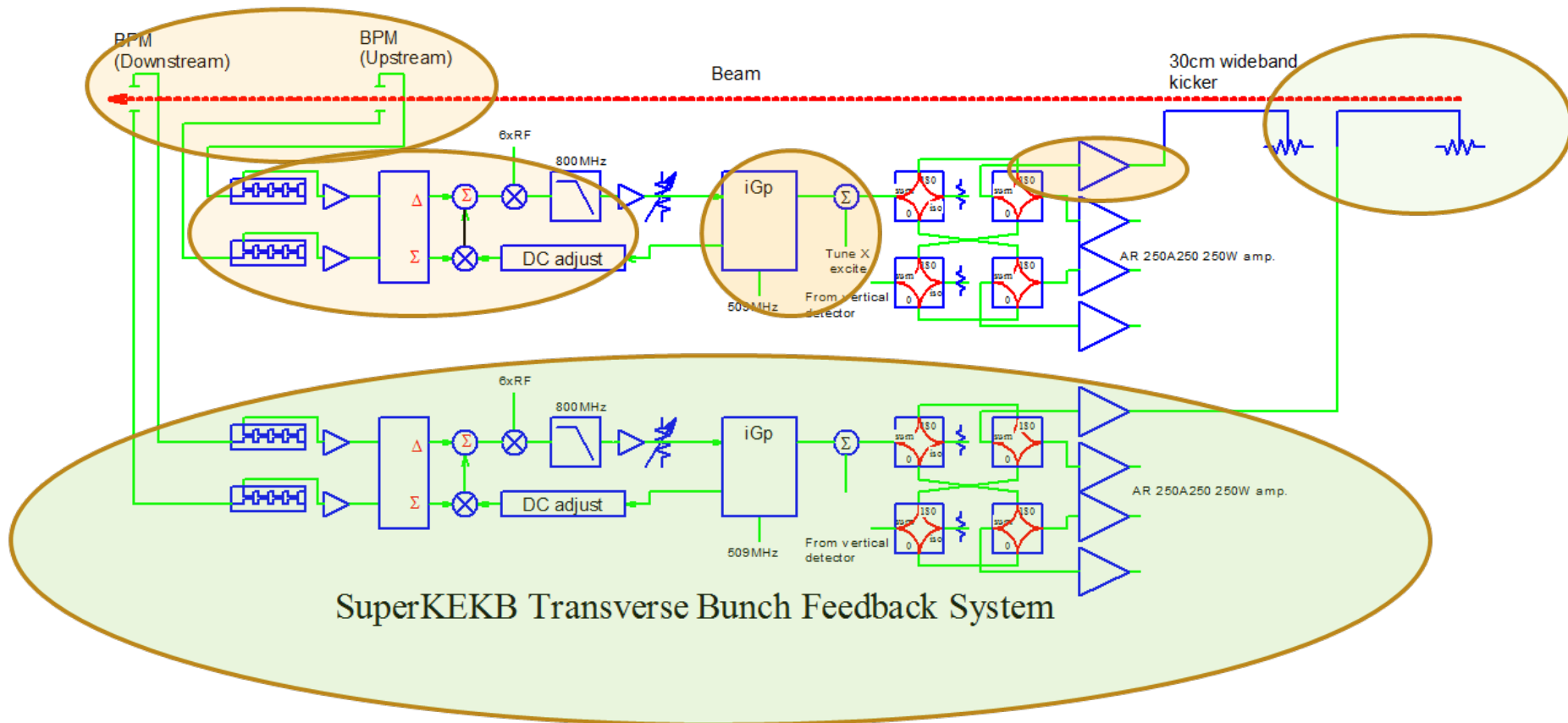
Might we need medium band detector?



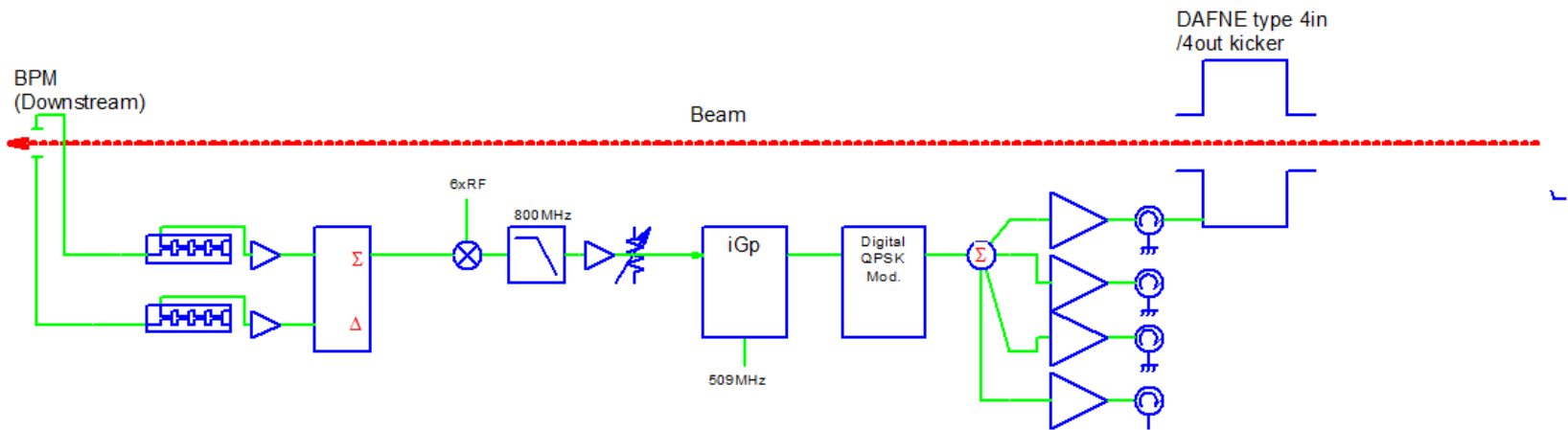
We have bought a Libera Brilliance+ with orbit feedback unit to evaluate the performance.



SuperKEKB Transverse FB plan



SuperKEKB Longitudinal FB plan

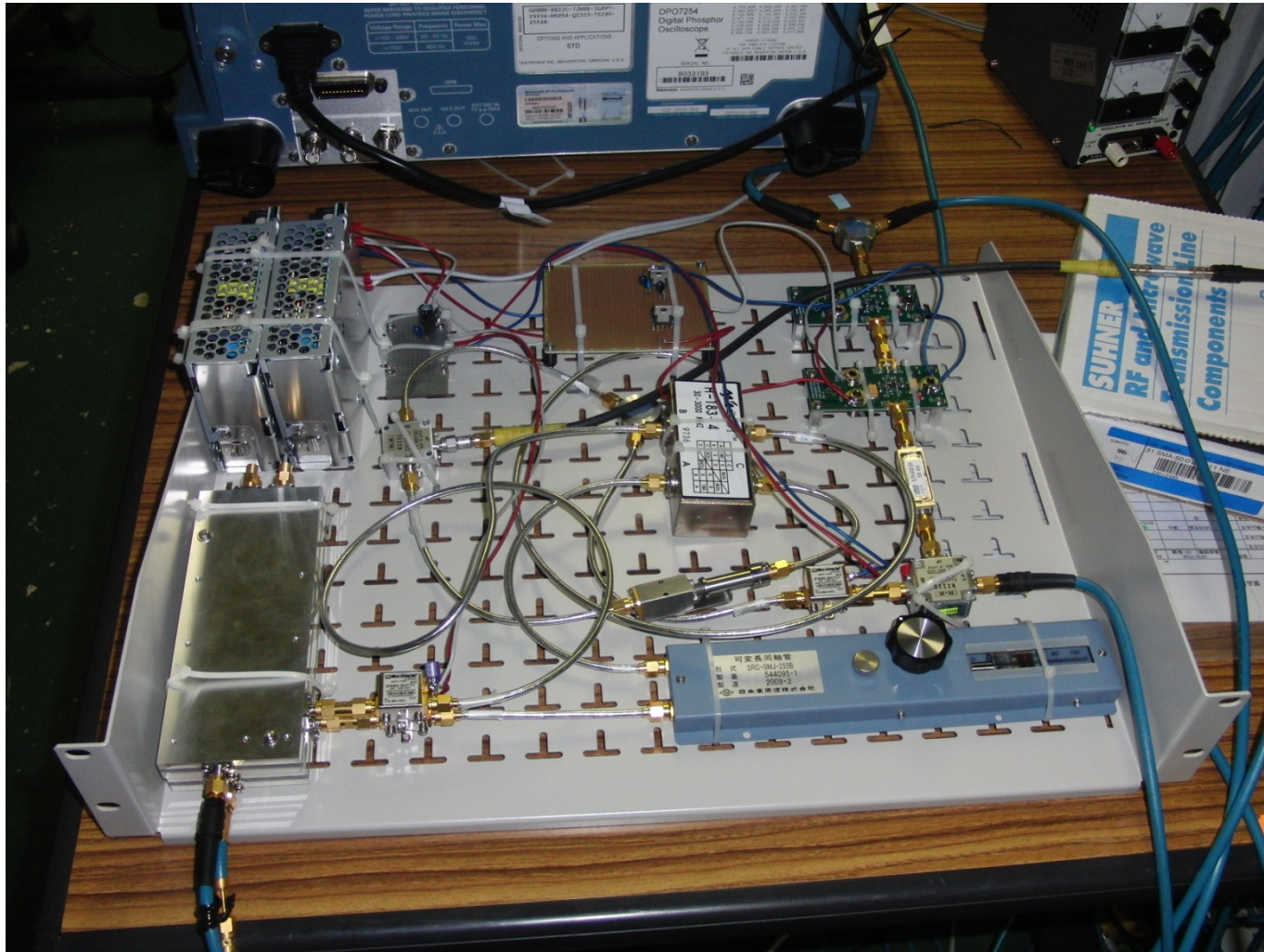


SuperKEKB Longitudinal Bunch Feedback System

Install L-FB in LER only. HER is optional.

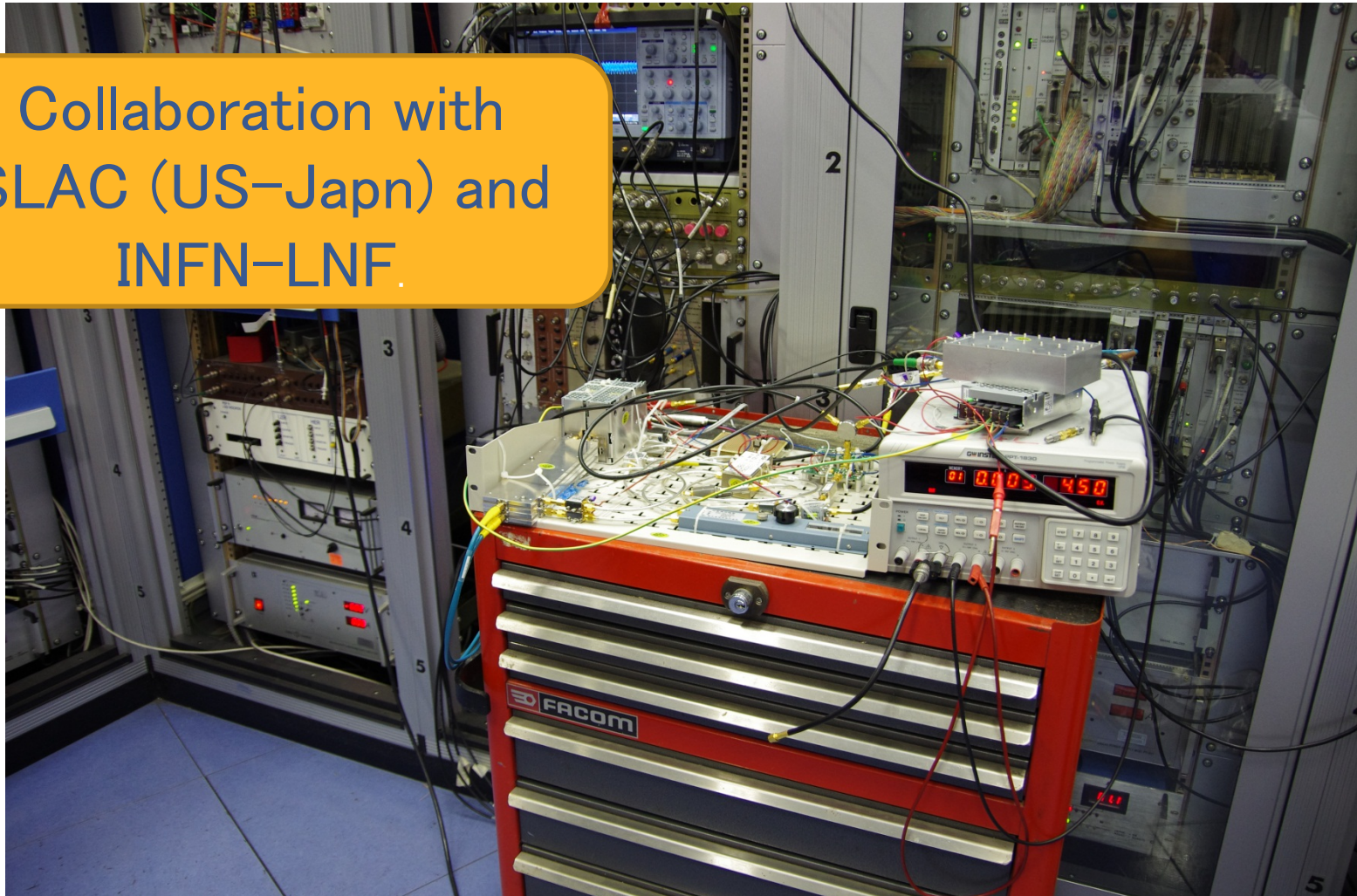
Considering to use 4 DAFNE type kicker, with 2-input, 2-output ports for larger capture range.

Bunch position detector prototype



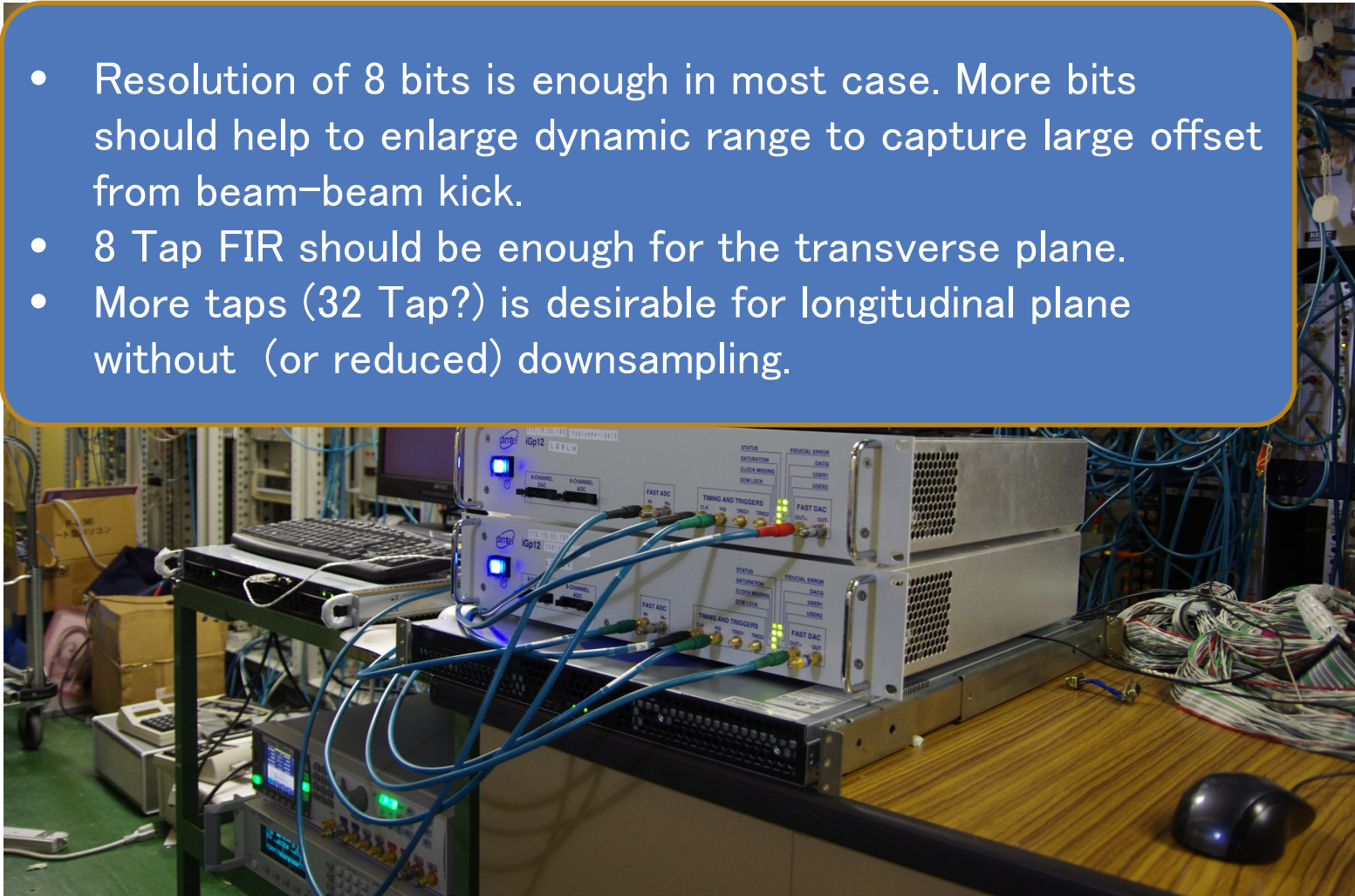
DAFNE FB experiment

Collaboration with
SLAC (US-Japn) and
INFN-LNF.



Feedback digital filter(iGp12)

- Resolution of 8 bits is enough in most case. More bits should help to enlarge dynamic range to capture large offset from beam-beam kick.
- 8 Tap FIR should be enough for the transverse plane.
- More taps (32 Tap?) is desirable for longitudinal plane without (or reduced) downsampling.



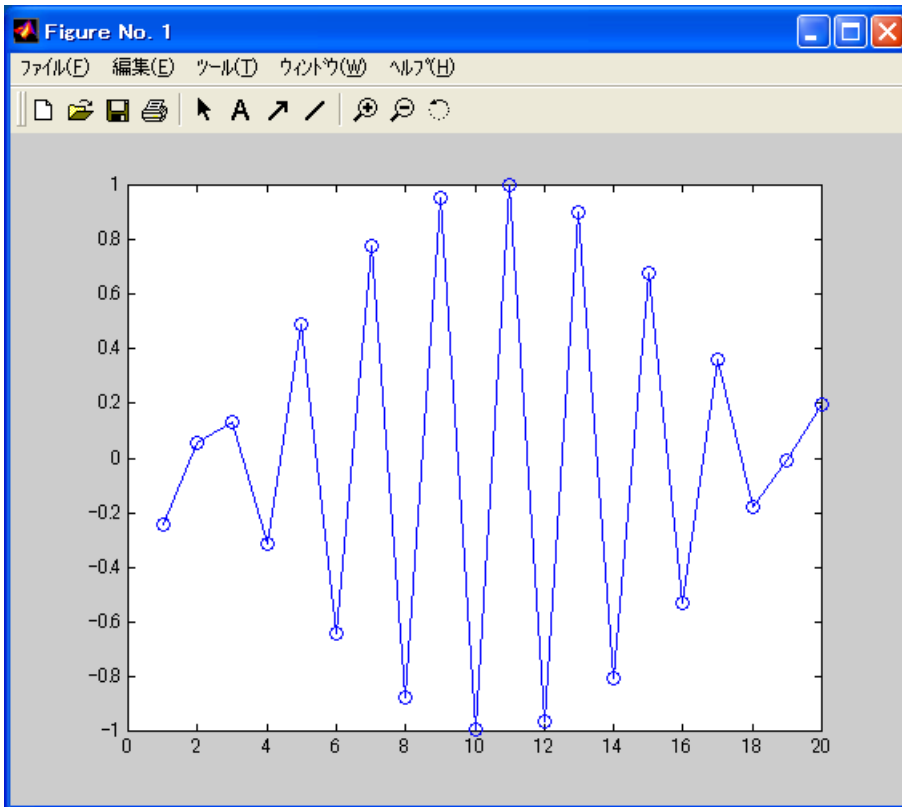
LER(1604) optics

- **Tune (*.53, *.57)**
- **Phase advance between FB monitor, Kicker**
 - PPU1(U) to PPU2(D): H:62deg, V:53 deg
 - PPU1(U) to Kicker (include one turn): H 170 deg, V: 177 deg
 - PPU2(D) to Kicker (include one turn):H 62 deg, V:53 deg
- **Phase advance from collision point to FB detector**
 - PPU1(U): H: 346deg, V:153deg
 - PPU2(D):H 48deg, V:205deg
- **Phase advance from injection point**
 - PPU1(U): H 346 deg, V:43 deg
 - PPU2(D): H 48 deg, V:95 deg

HER(5605)

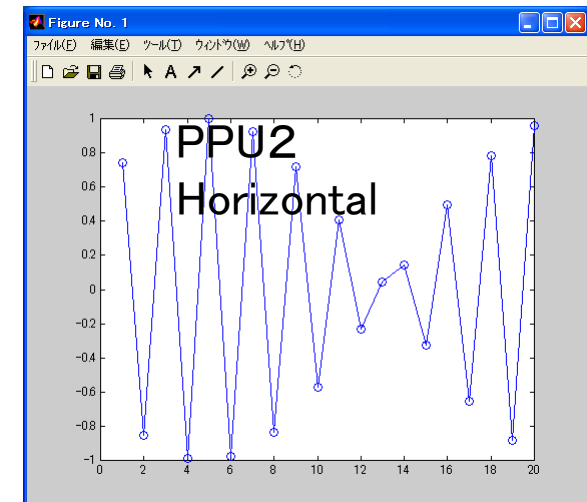
- **Tune (*.53, *.57)**
- **Phase advance between FB monitor, Kicker**
 - PPU1(U) to PPU2(D): H:200deg, V:42 deg
 - PPU1(U) to Kicker (include one turn): H 145 deg, V: 201 deg
 - PPU2(D) to Kicker (include one turn):H 307 deg, V:159 deg
- **Phase advance from collision point to FB detector**
 - PPU1(U): H: 245deg, V:173deg
 - PPU2(D):H 85deg, V:215deg
- **Phase advance from injection point**
 - PPU1(U): H 270 deg, V:335 deg
 - PPU2(D): H 108 deg, V:17 deg

Horizontal tune is near 0.5

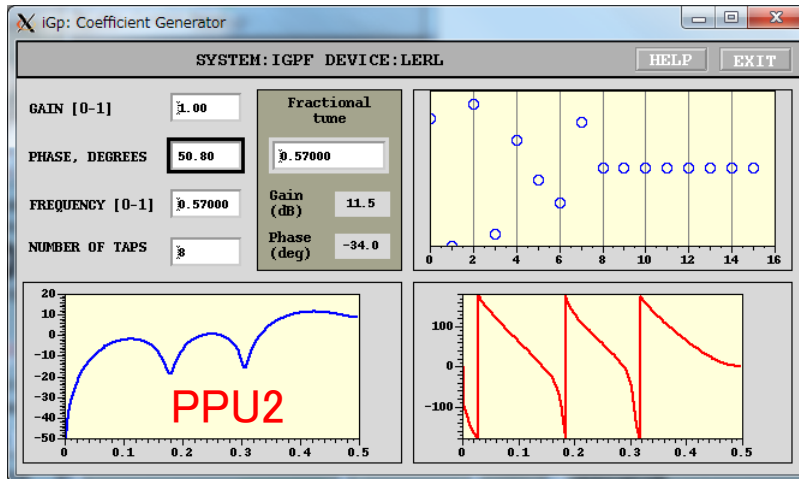


Simulated horizontal beam oscillation starting beam-beam kick measured at PPU1 (Upstream).

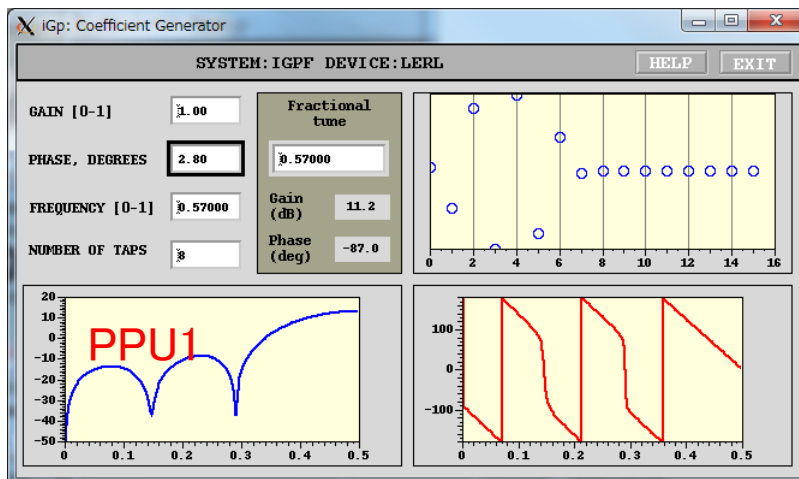
- Need several turns of revolution to observe real kick if the phase relation between the source and the monitor is not so good.
- Using two feedback loop with betatron phase advance around 90 deg might solve this difficulty.



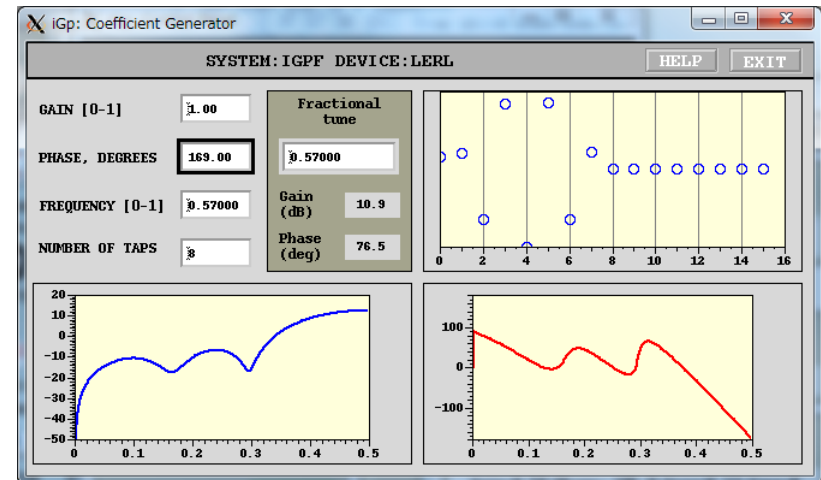
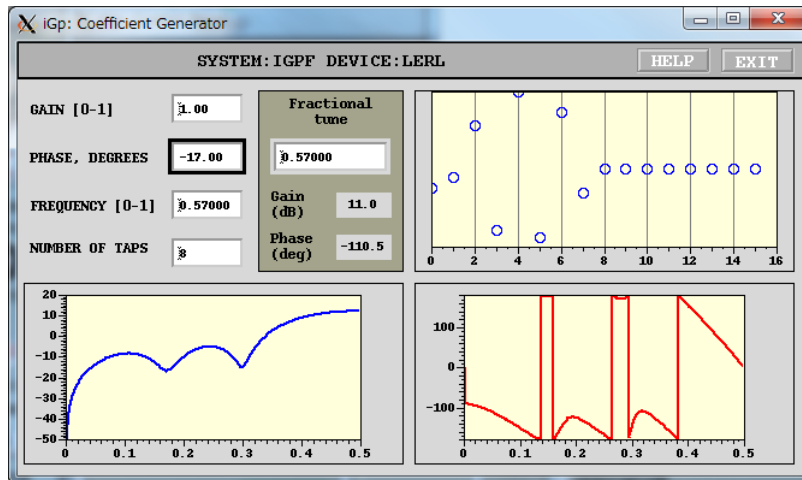
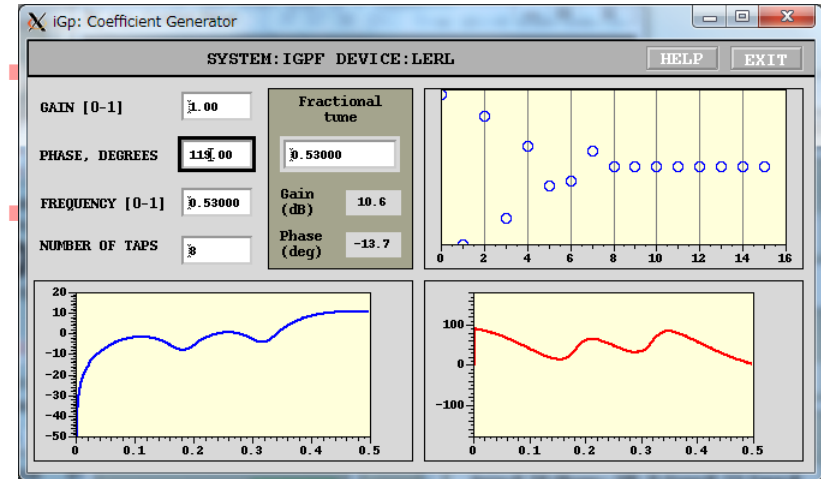
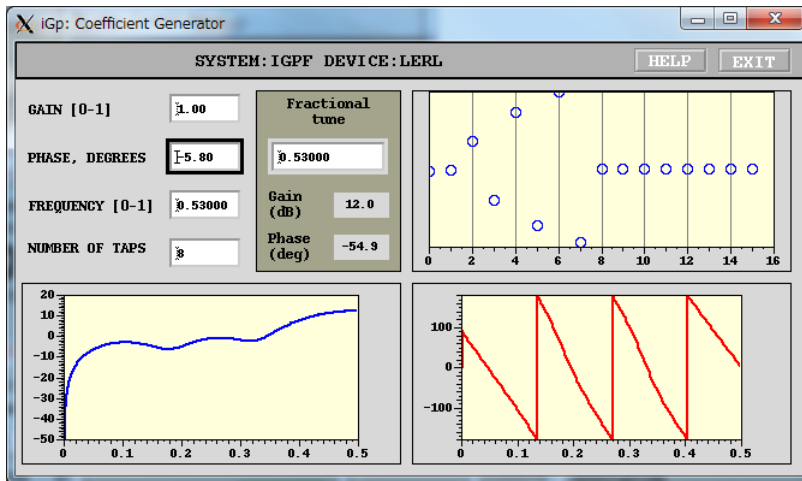
Phase shift by digital filter



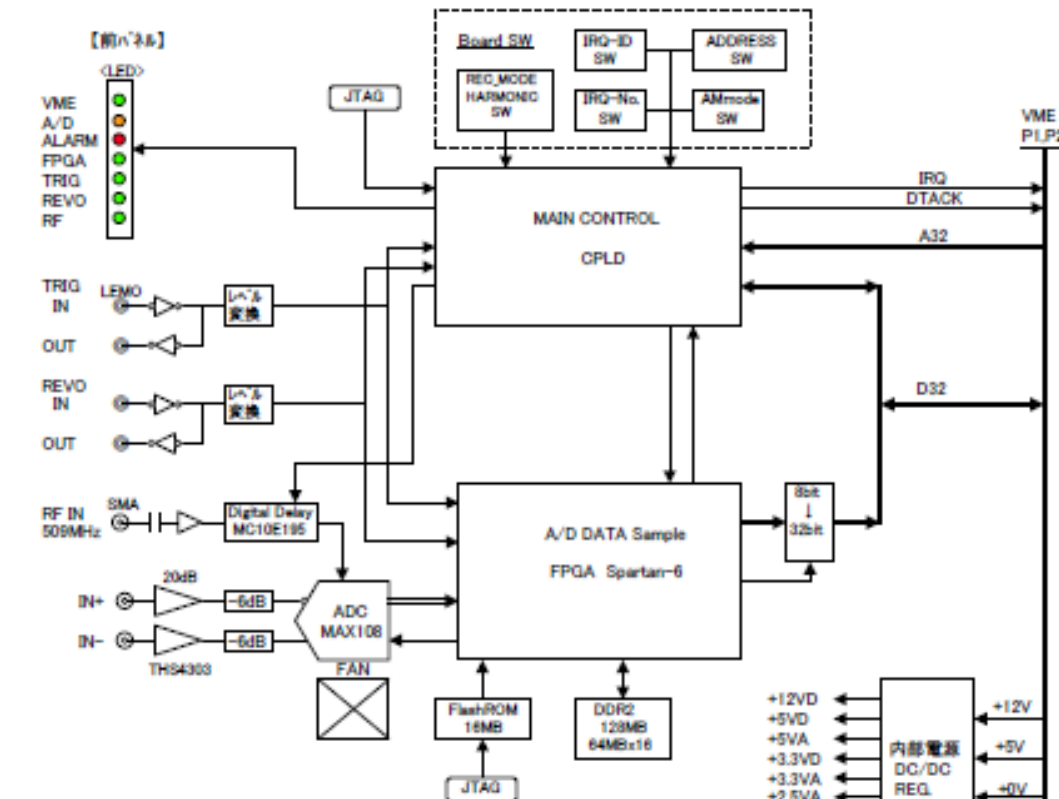
- Creating near 90deg phase shift in the digital filter makes the stability limit worse.
- LER (PPU1 and PPU2) might be acceptable.



HER PPU1 (U) situation



Bunch current monitor



MAX108 8bit ADC
Spartan6 FGPA
VME 2W size

Bunch current information will be send through reflective memory (real time) to the bucket selection system during injection period.

Schedule

- **BPM heads for LER antechamber**
 - 1/2 of needed BPM will be delivered soon. The rest will be fabricated in the next fiscal year.
- **509MHz narrow band detector**
 - Final tuning to improve the performance (S/N, linearity) in progress.
 - Mass production will be starting on next fiscal year.
- **Gated turn-by-turn monitor**
 - Prototype test is in progress (with many difficulty).
 - 2nd trial production might be needed.
 - Waiting for the decision by the optics group for the place (and the total number) of the monitor.

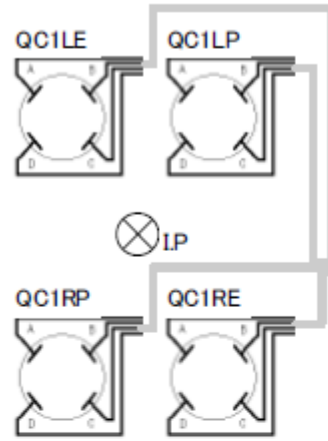
Schedule (cont.)

- **Fast orbit feedback**
 - 2nd trial production of the detector (uTCA) is planned in the next FY.
 - Feedback processor unit will also be ready.
 - Simulation work using Simulink/Matlab is in progress.
- **Bunch by bunch feedback system**
 - Feedthroughs (button, high power) will be delivered by E/Mar.
 - High power amplifiers (10k–255MHz 500W x 8, 0.8–1.8GHz 500W x 8) will be delivered by E/Mar..
 - Waiting for the decision of the chamber structure around the feedback systems to design the vacuum components such as monitor, feedback kicker.
 - iGp12 will be used for the digital filter.
 - Continue the collaboration with SLAC and INFN-LNF.

backup

軌道フィードバックBPM データ転送・軌道演算システム Ver. 1.01

BPMはQC1に付いている4台

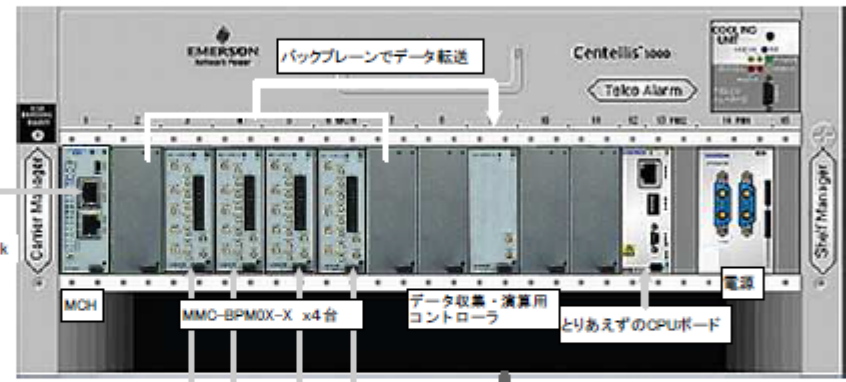


BFM信号処理回路 (MMC-BPM01-B) データ出力形式

出力データ	X, Yビーム位置 (mm)
データ出力レート	5 kHz
データフォーマット	?
データビット数	固定小数点で24bits以上
データ出力インターフェース	GbE, PCI Express μTGA Back planeを使用
測定の同期	?

データ収集・演算用コントローラ (信号処理回路のデジタル部分を使用する)

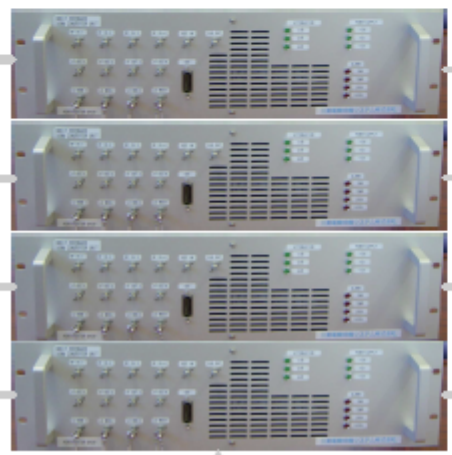
信号処理回路とのインターフェース	GbE, PCI Express μTGAの μTGA Back planeでデータをやり取り 100HzするならLinux? 100Hzするなら
OS	?
EPICSは動作させるのか	データ収集、出力、演算を5kHzの Ratencyで行なえる必要あり?
要求演算性能	固定小数点で24bits以上? 最初は4台 簡単自由にも動作中にも変更可能なこと
演算結果出力レート	5 kHz
必要演算精度	?
BFM割合分演算するのか	?
演算式、パラメータ	リモートでFlashROM書き換え



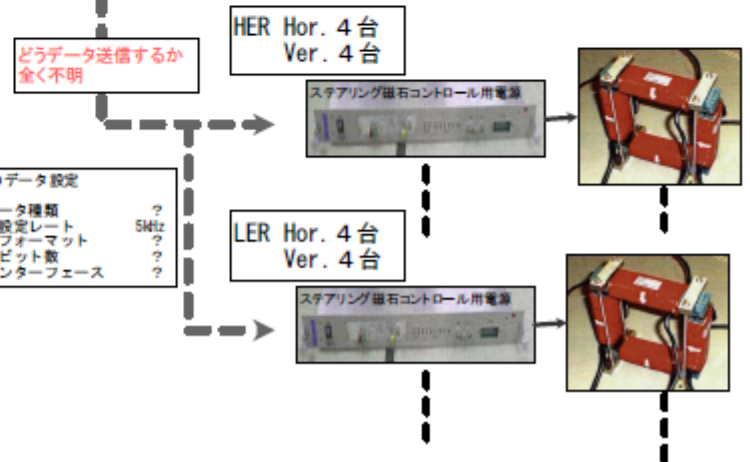
データ収集・演算用コントローラの外部との通信

遅いOD測定 (KEKBでいう所のOD) へ
演算結果、Bump情報を通知する必要あり
データ収集・演算用コントローラの処理に
余裕がある場合、IOCを実装しEPICSにて
必要な通信を行なうのがよいのか?

アナログ信号処理部



RF clock供給 508.887MHz

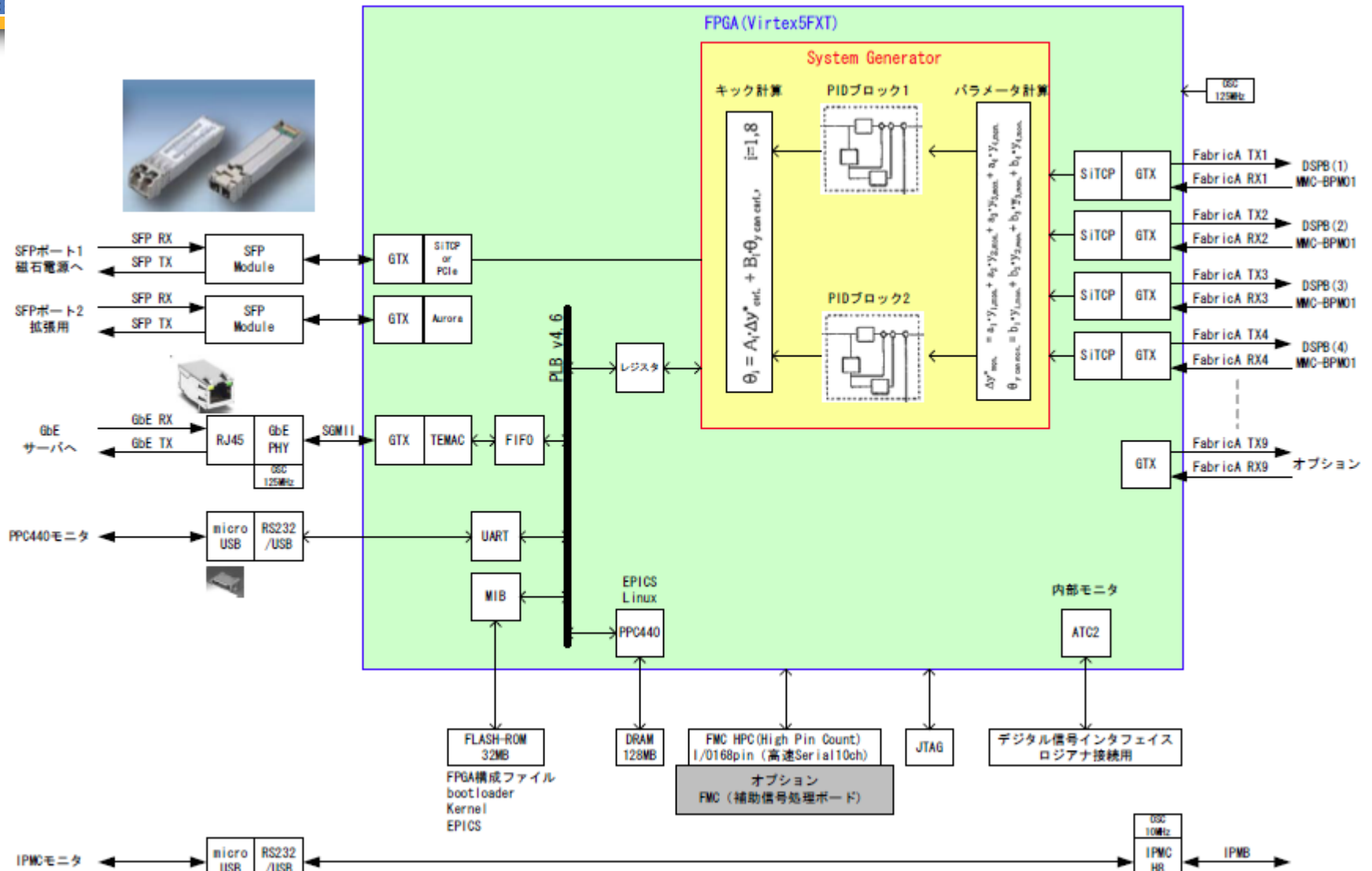


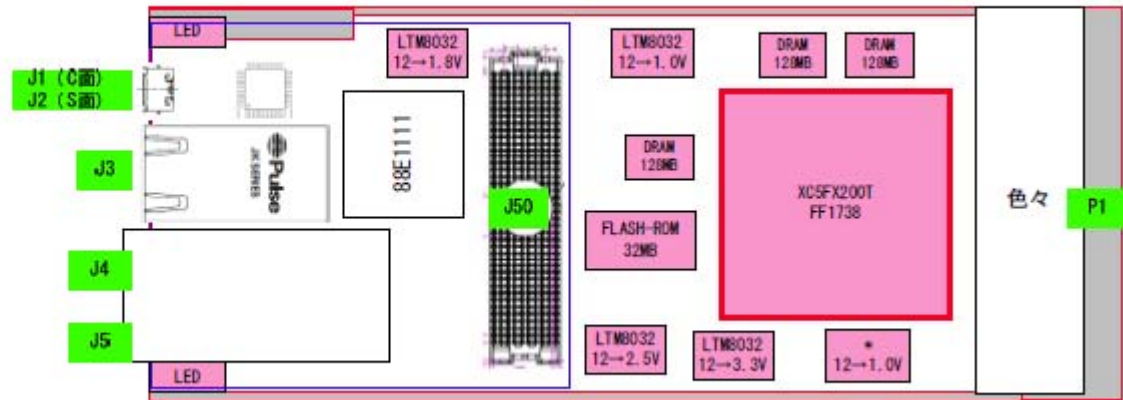
電源へのデータ設定

磁カデータ種類	?
データ設定レート	5kHz
データフォーマット	?
データビット数	?
磁カインターフェース	?

HER Hor. 4台
Ver. 4台

LER Hor. 4台
Ver. 4台





SO-DIMM type FPGA(SP6-LX45)



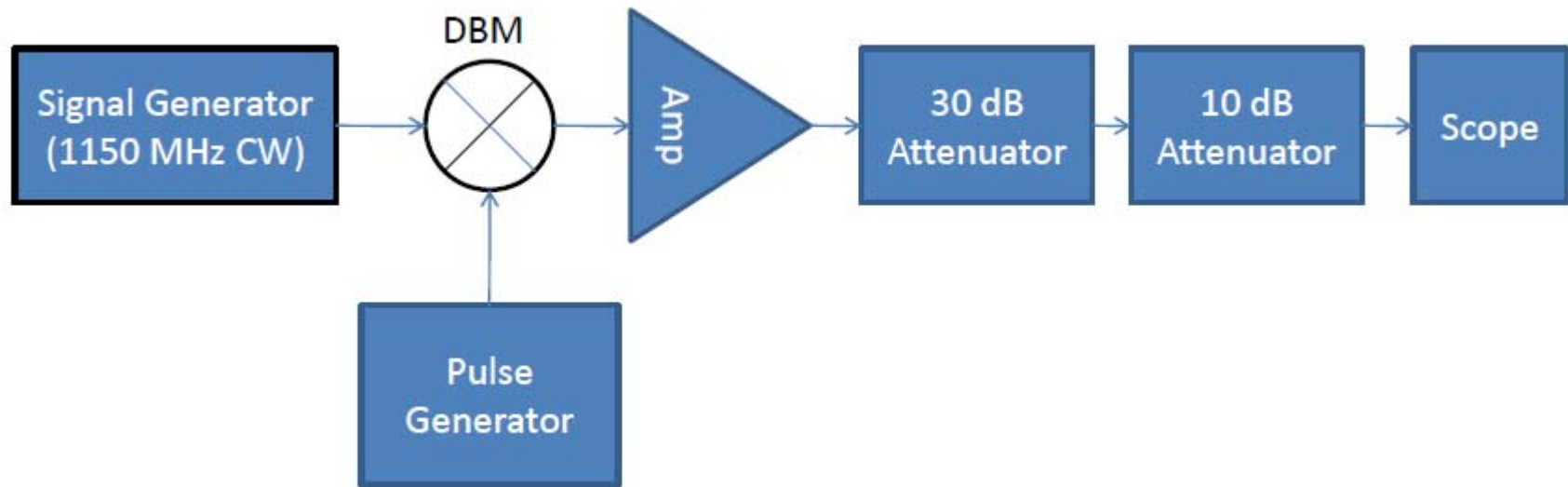
<http://www.enclustra.com/en/products/fpga-modules/mars-mx1/>

Milmega

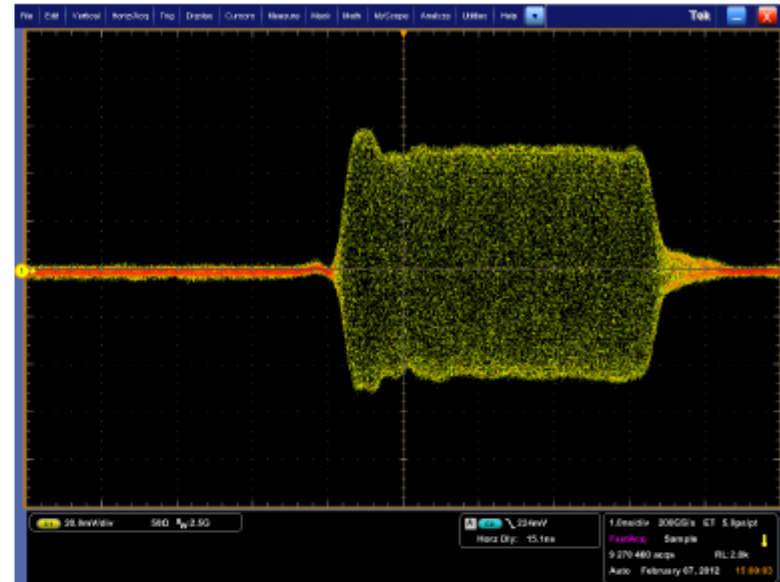


R&K

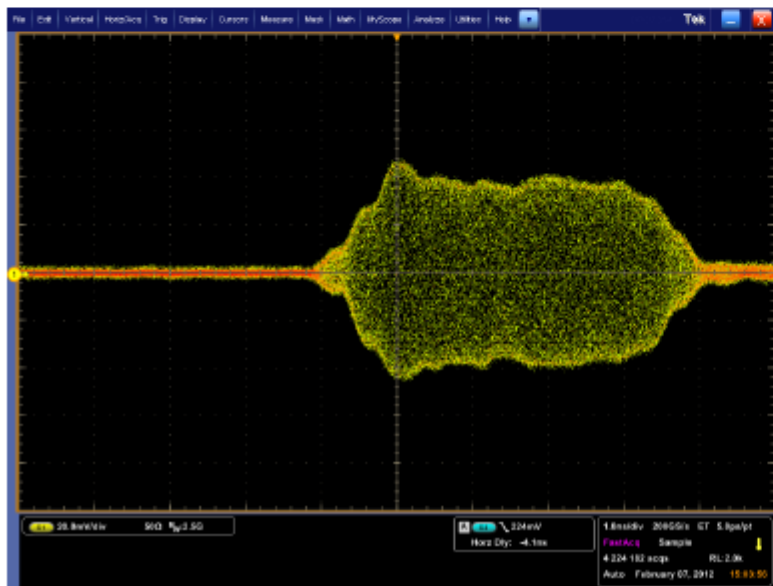




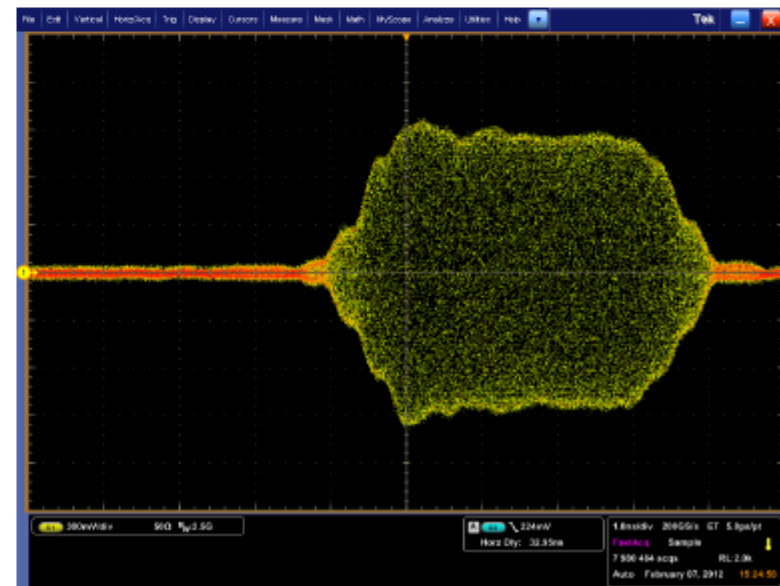
入力:
1.15 GHz
パルス幅4 ns



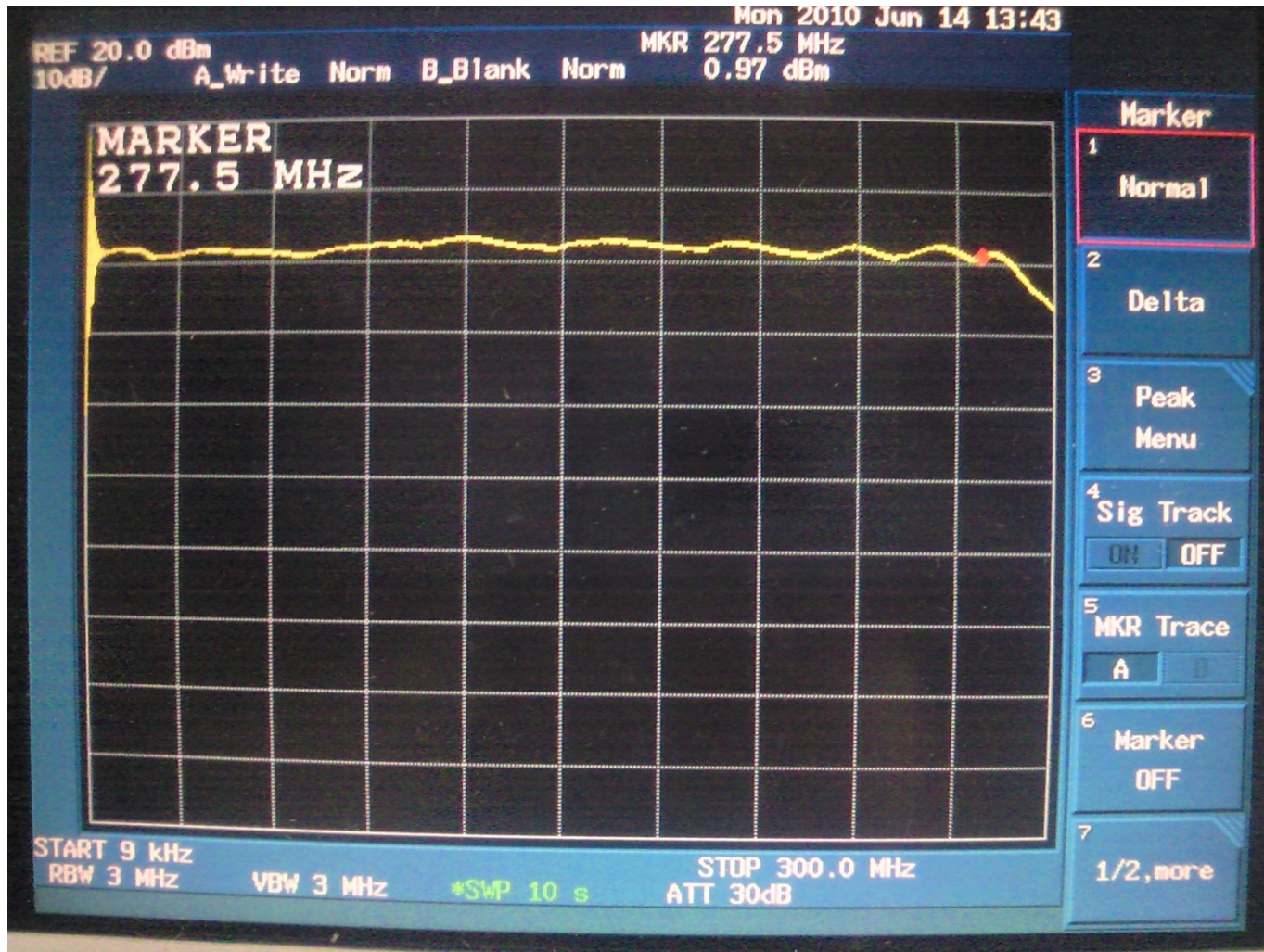
出力: Milmegaのアンプ



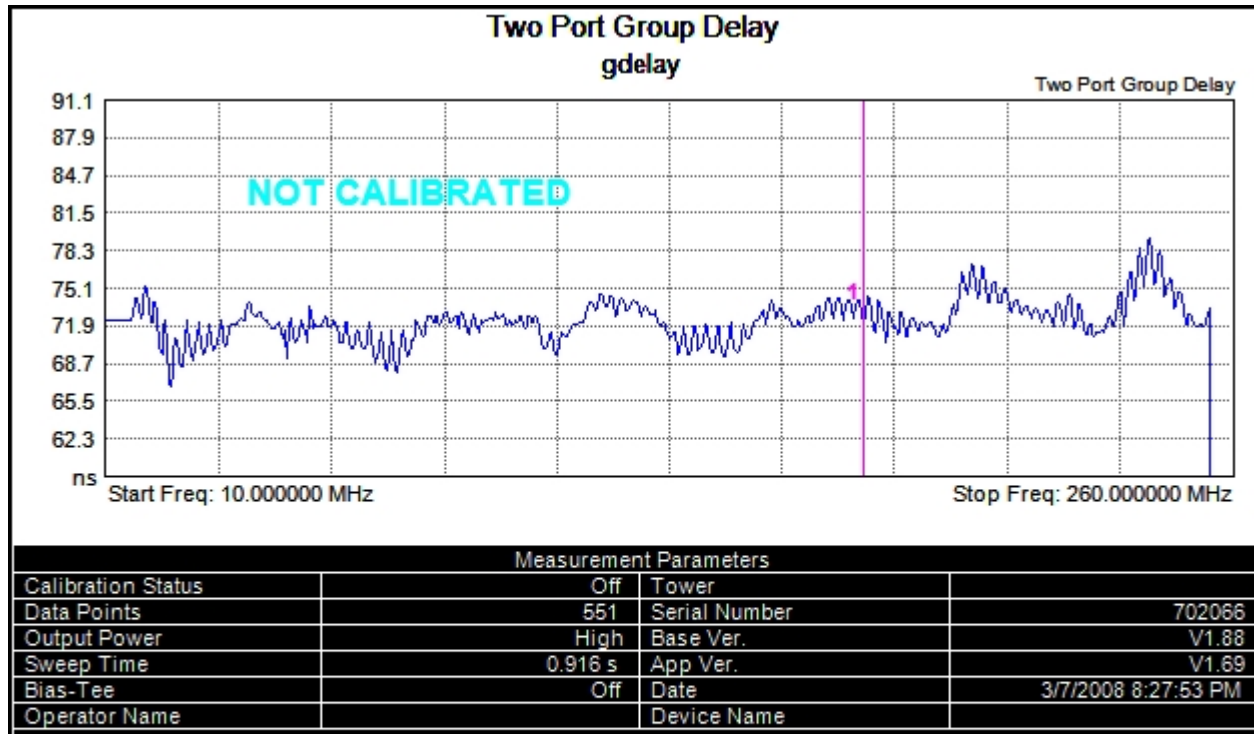
出力: R&Kのアンプ



周波数応答(-10dBm)

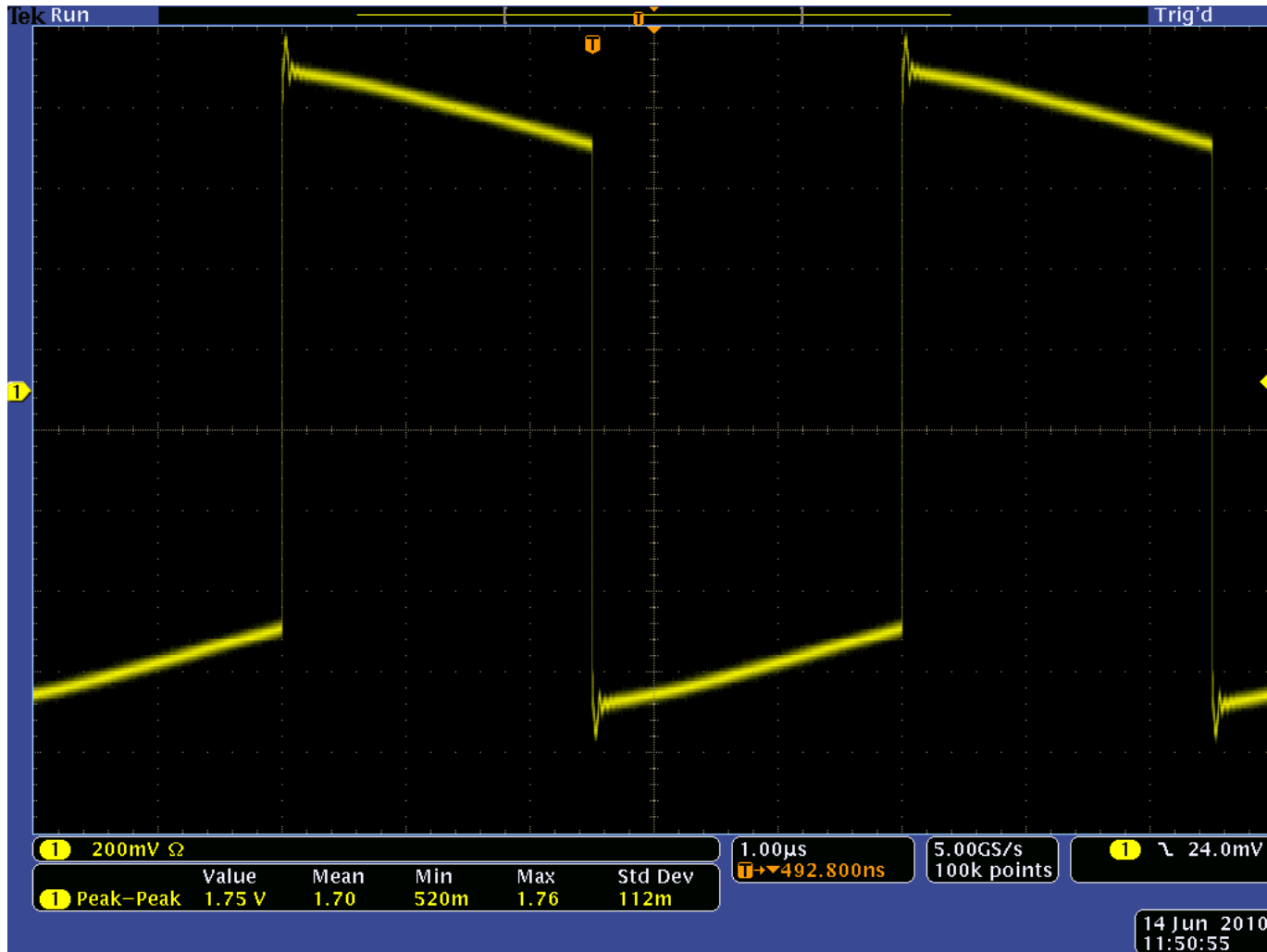


群遅延特性

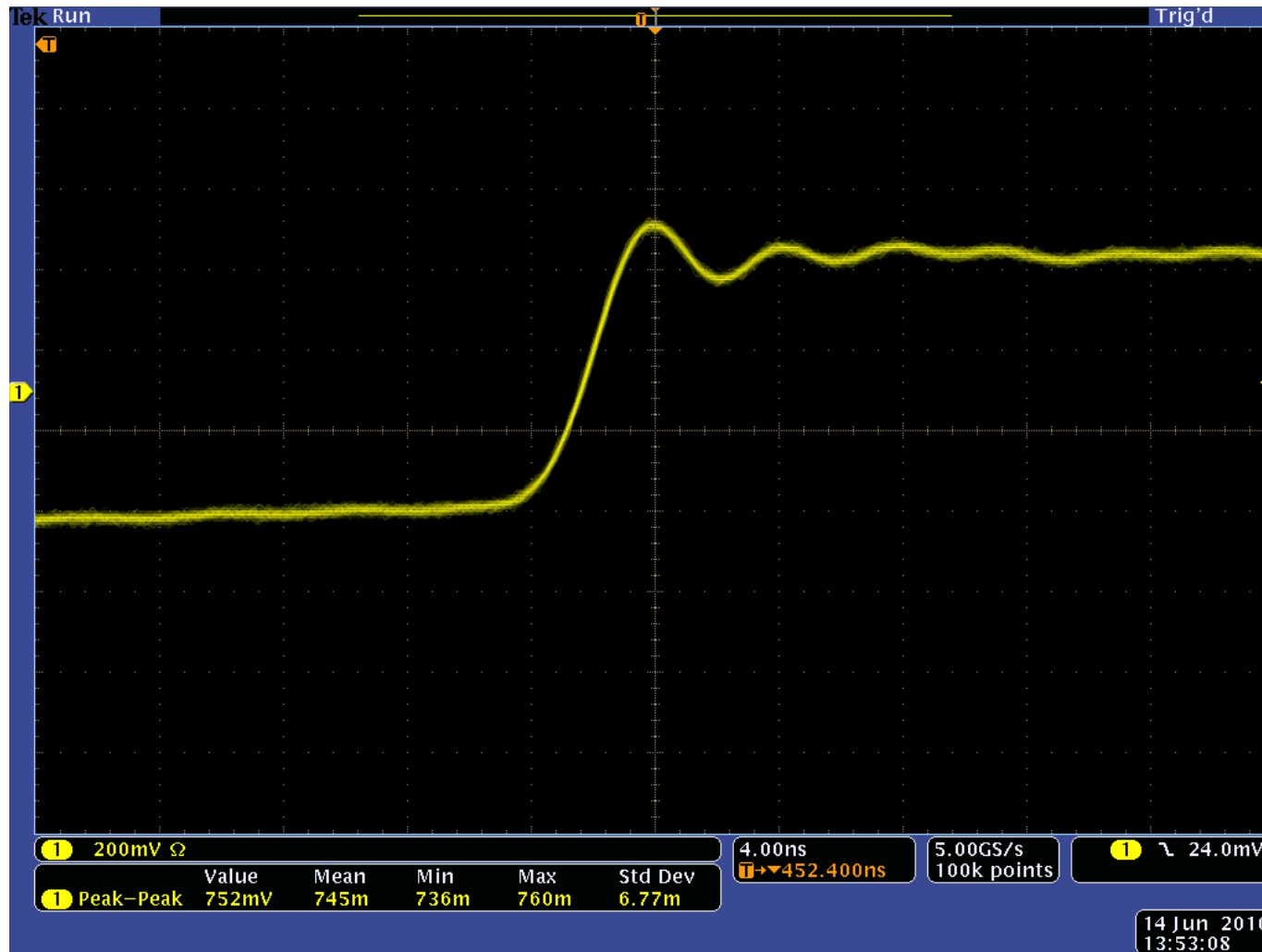


Measurement Parameters			
Calibration Status	Off	Tower	
Data Points	551	Serial Number	702066
Output Power	High	Base Ver.	V1.88
Sweep Time	0.916 s	App Ver.	V1.69
Bias-Tee	Off	Date	3/7/2008 8:27:53 PM
Operator Name		Device Name	

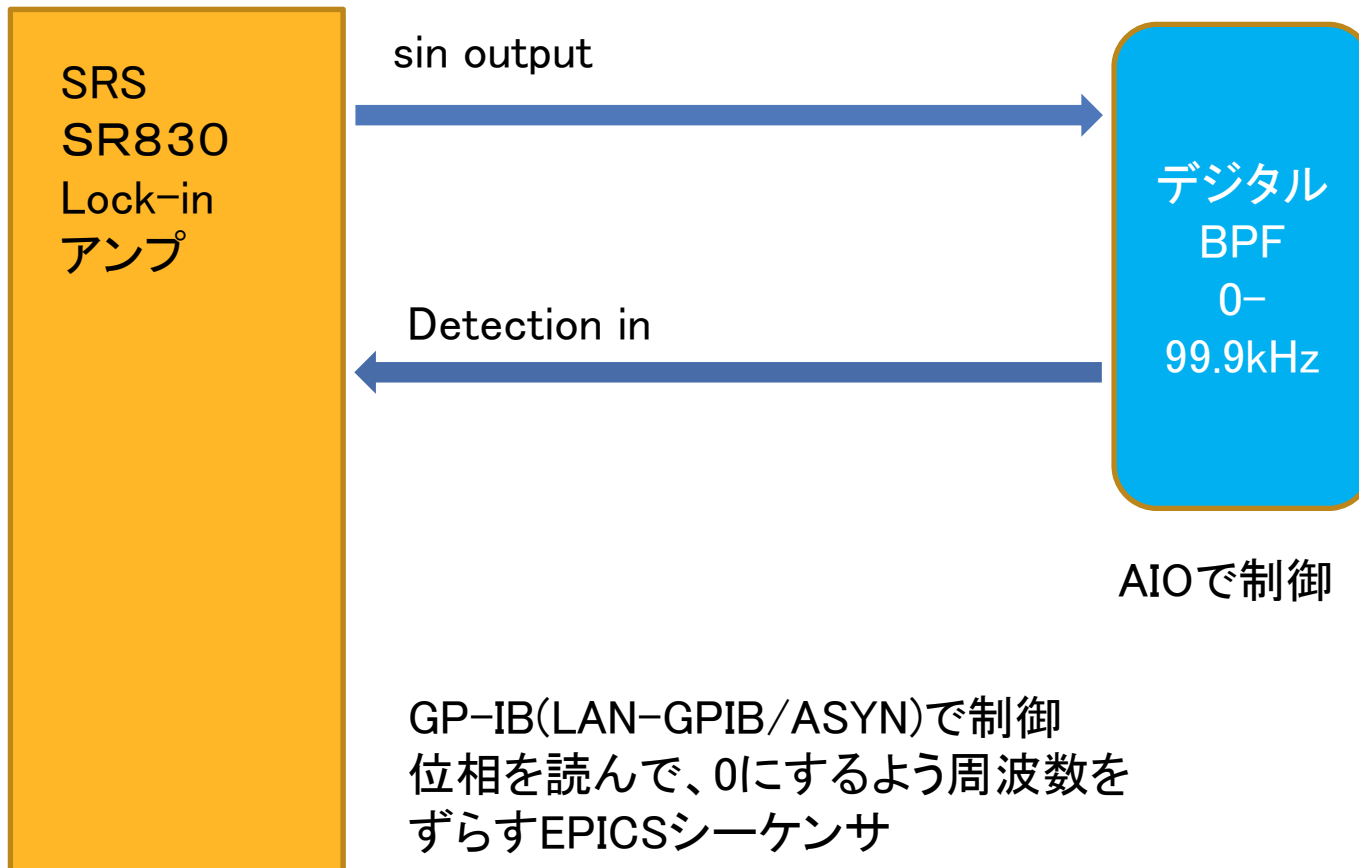
420mV_{pp}(500W)



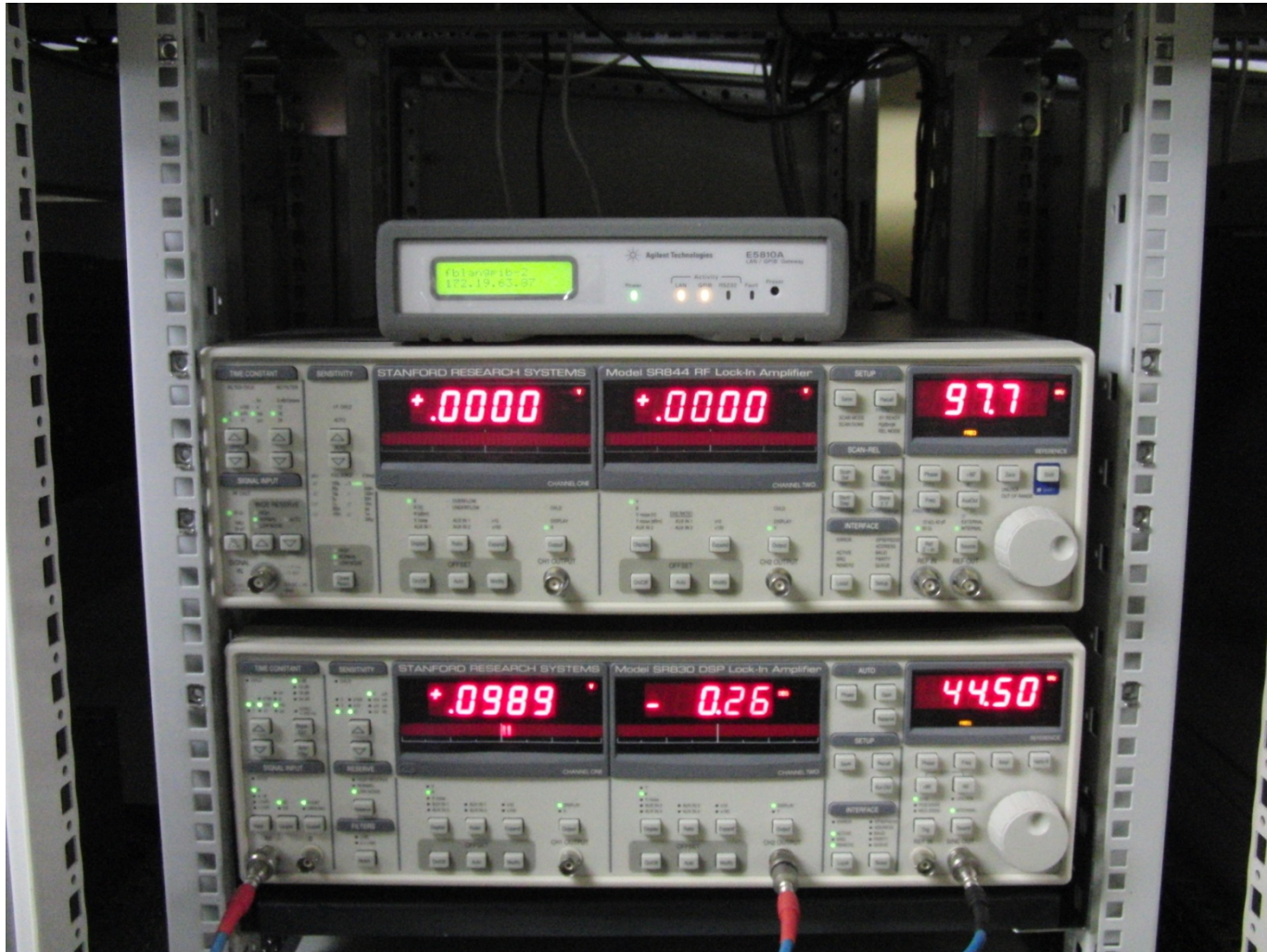
立ち上がり(240MHz FG)



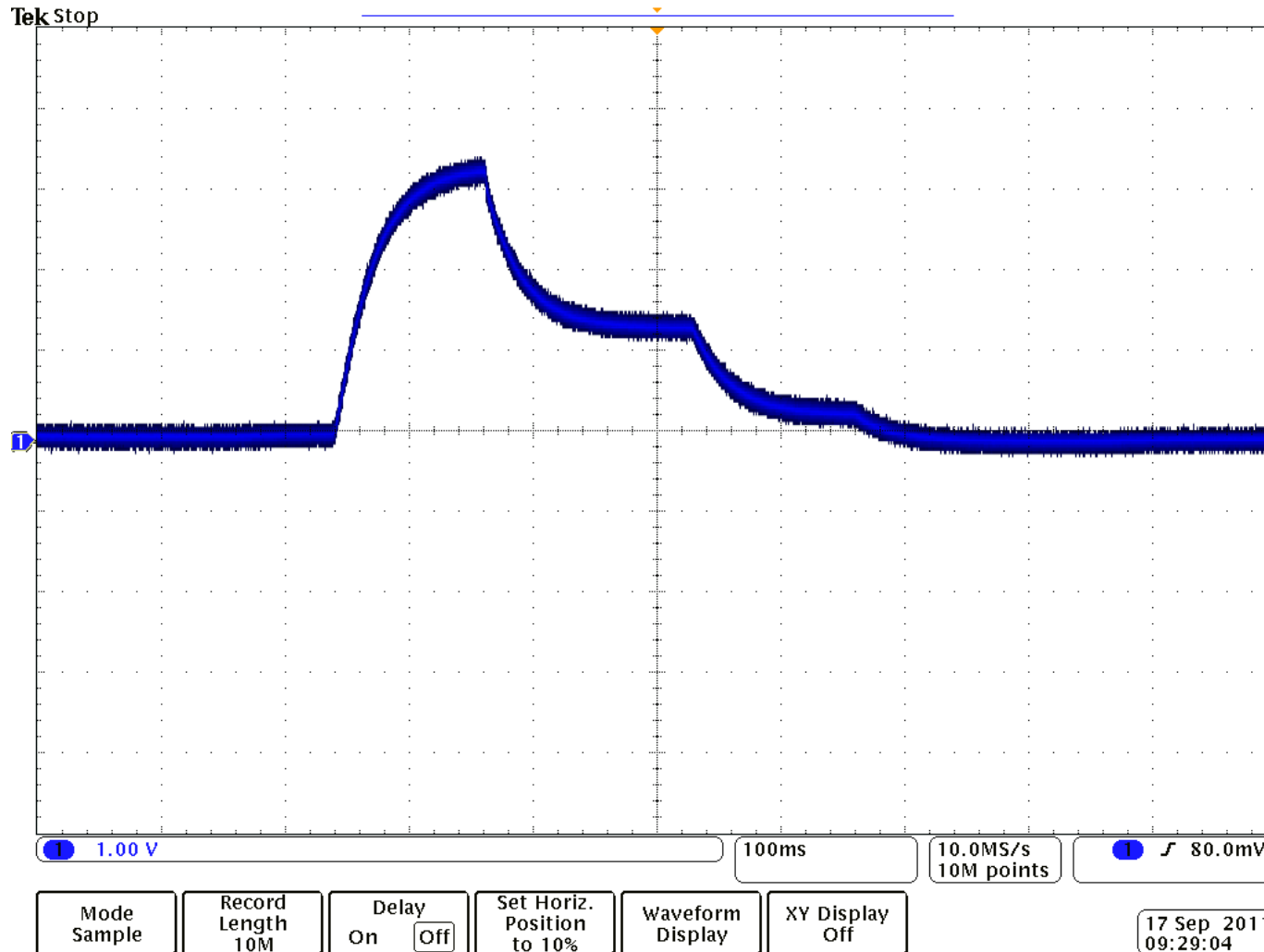
SR830の場合



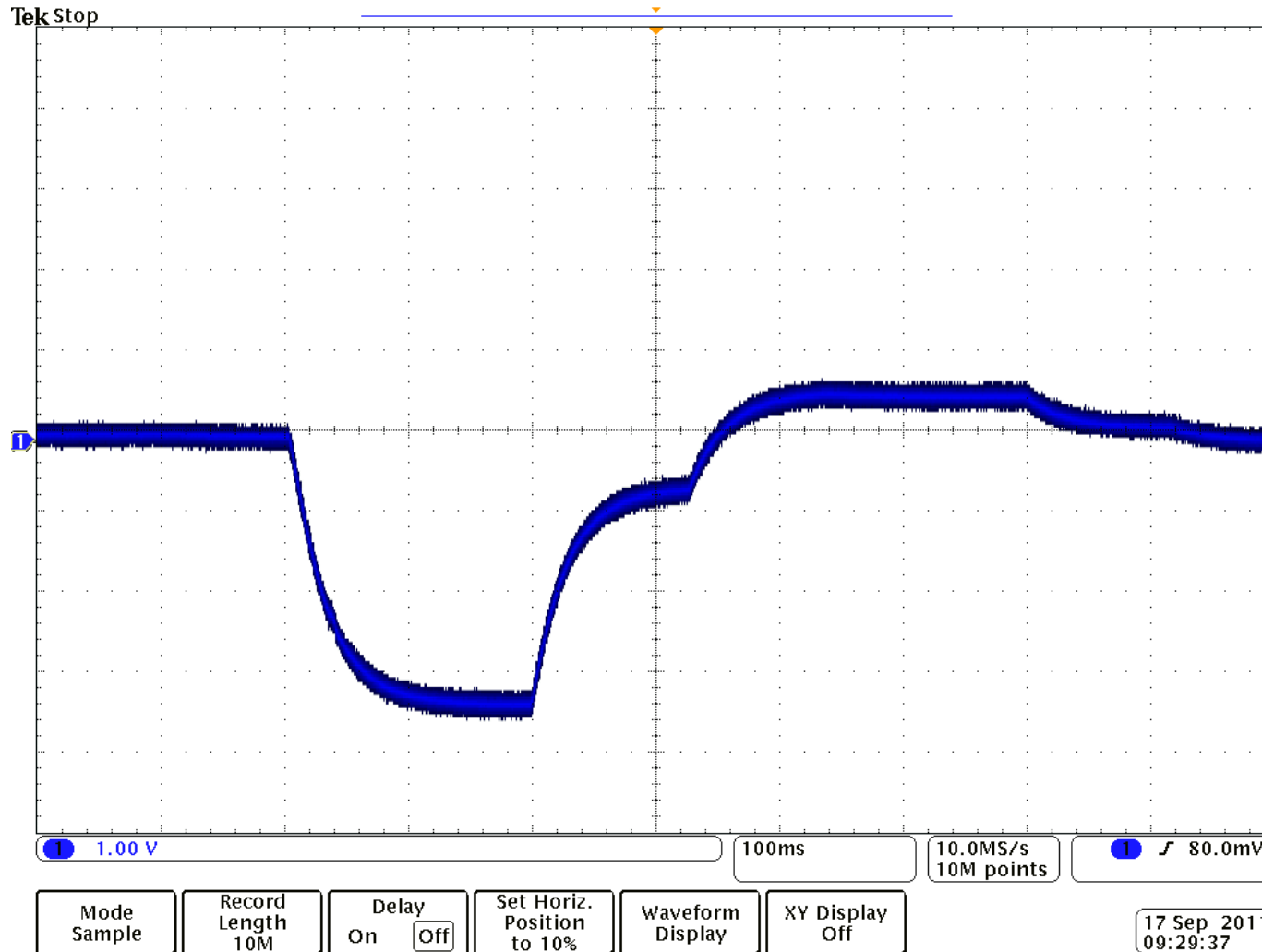
Lock-inアンプ



gain 0.8、44k-45kステップ



gain0.8 45k-44kステップ



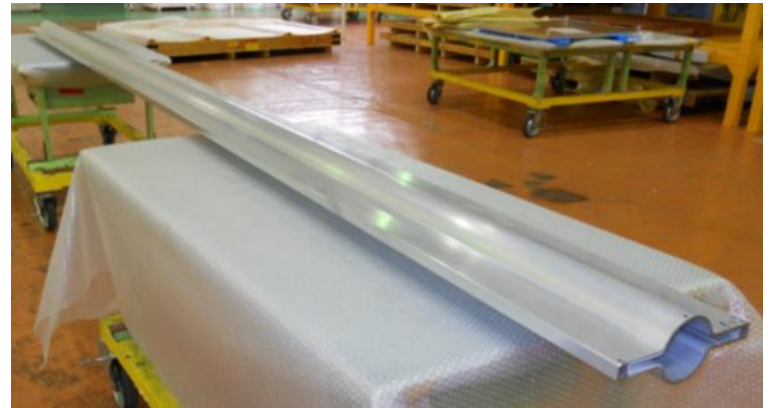
Vacuum chamber

- Aluminum alloy antechamber
- cutoff frequency < 1 GHz

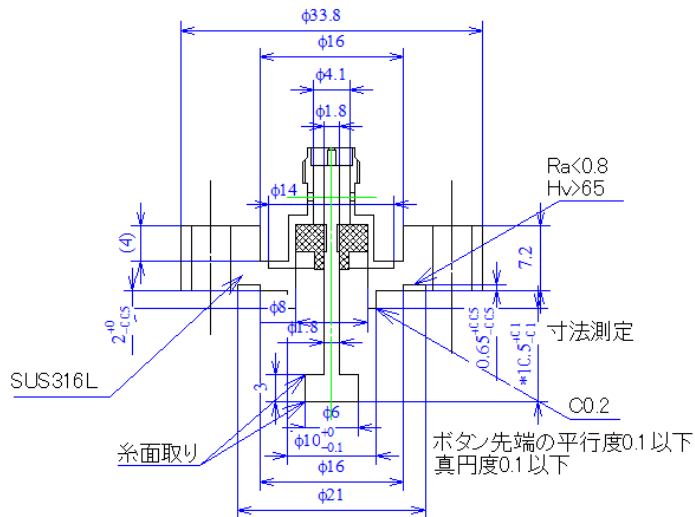
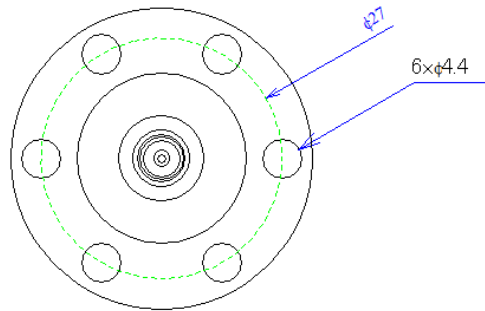
Aluminum-alloy duct



Aluminum-alloy duct



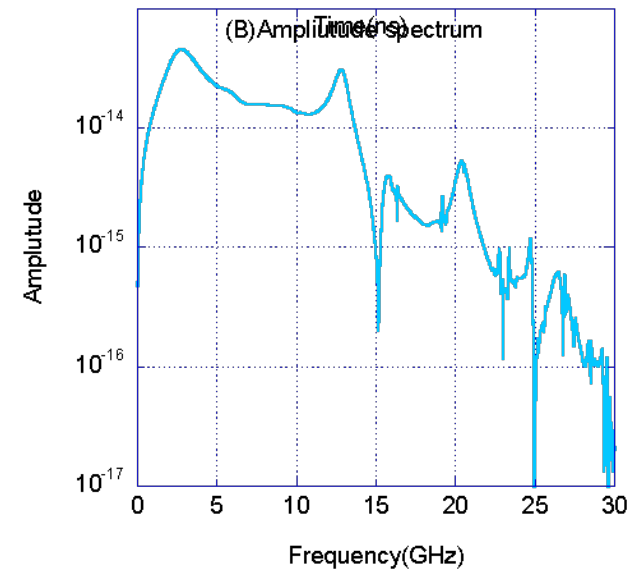
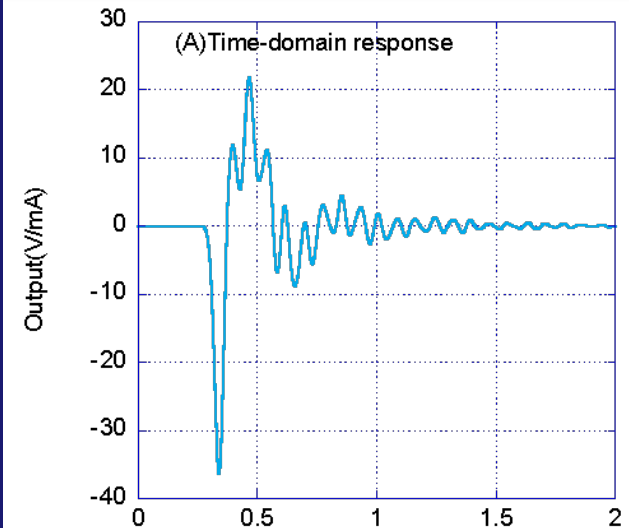
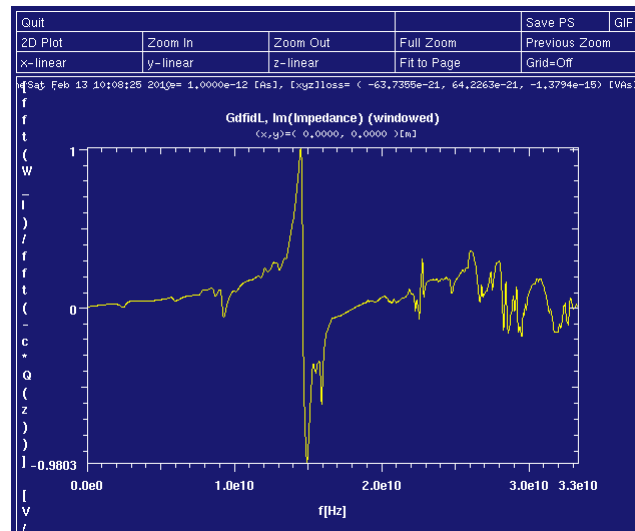
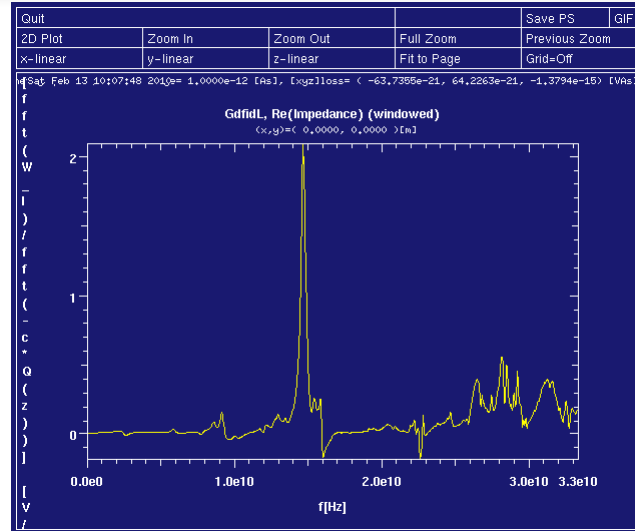
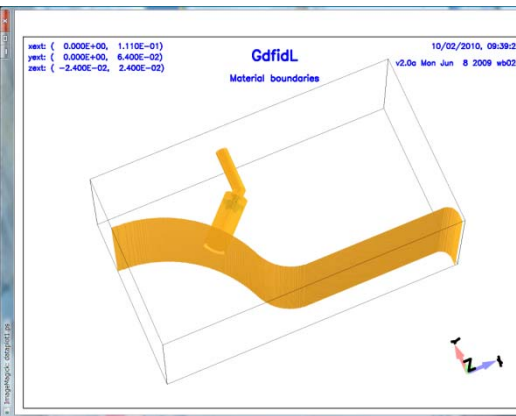
BPM head



SuperKEKB用BPM model-E1
 作図: M.Tobiyama 6/Oct/2006
 修正: M.Tobiyama 8/Nov/2006



Impedance/button output simulation



RF to No.1 (SW off)



RF to No.1 (SW ON)



RF to No.2 (SW ON)



RF to No.2(SW OFF)

