# Status of the SuperKEKB Accelerator Control System

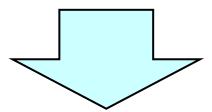
M. Iwasaki (KEK)
for the SuperKEKB accelerator control group

# Introduction

# The KEKB accelerator is upgraded to SuperKEKB

## x40 higher luminosity

- More precise, reliable, and robust accelerator control system is required.
- Many accelerator components are upgraded.



Reliable and robust network system is required.

<u>Device controllers</u> (software/hardware) for the accelerator components should be upgraded.

# What we did in JFY2013

## 1. New network system construction

Wider band-width (100MbE → 10GbE), Redundant system, New network configurations, Wireless LAN system installations, ...

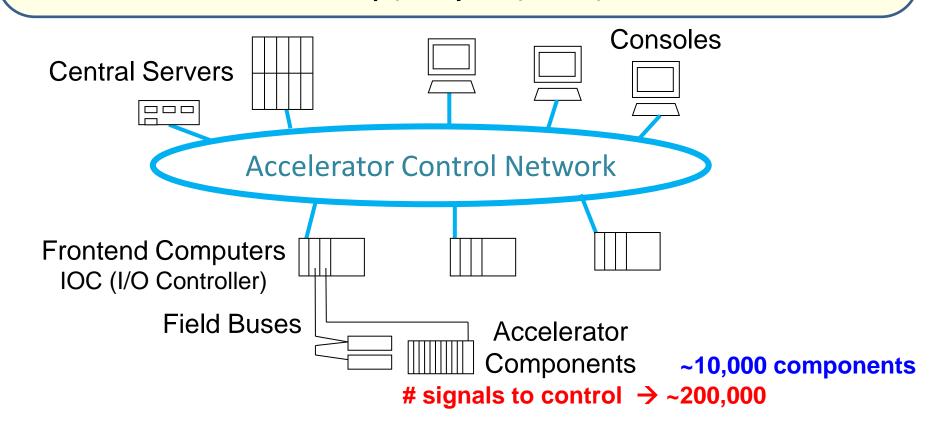
## 2. Device controller upgrade & implementation

Vacuum system, LLRF, Magnet power supply, Safety system, QCS cryogenic monitoring system, ...

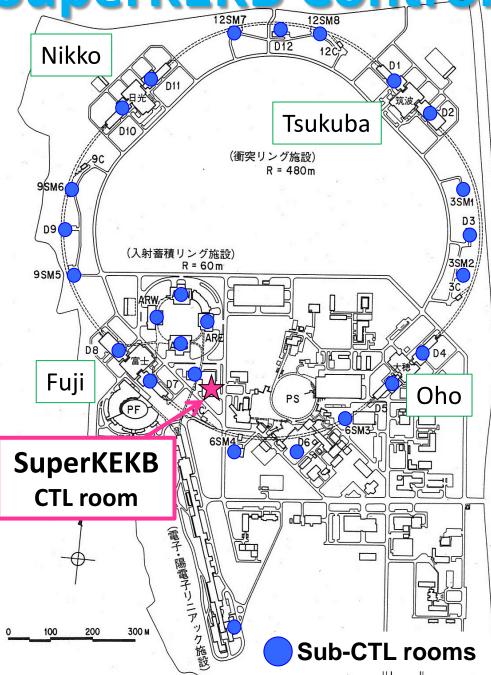
- 3. Additional new data archiving system
- 4. Beam abort system R&D
- 5. Timing system R&D
- 6. Renovation of the computing room

# SuperKEKB Control System

- EPICS is used as the main software to control the accelerator
  - 2 layer model
    - OPI (Operation Interface) --- operation programs on central servers
    - IOC (I/O Controller) --- equipment controls on frontend computers
- Scripting Languages are used for the operation programs
   SAD Script/Tk Python/Tk Tcl/Tk

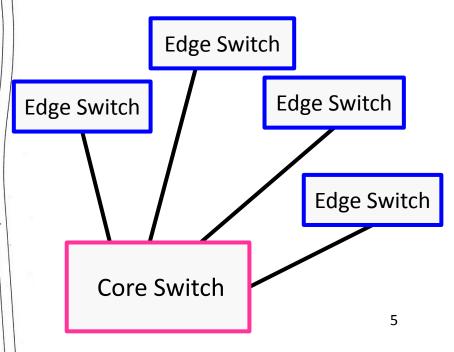


SuperKEKB Control Network System



## Star network topology

- Main network switch (core switch)
   is located at the SuperKEKB CTL room.
- All network switches (edge switches) in the 26 sub CTL rooms connect to the main network switch.



# Upgrade of the network system

## In JFY2013, the control network system is upgraded.

1. Wider band-width data transfer (100MbE → 10GbE)
Replace 100MbE switches to 10GbE ones.

### 2. Redundant system

- Install additional optical cables.
- All edge switches are connected to the core switch via both 10GbE and 1GbE lines, and form the active/standby configuration.

### 3. <u>Direct connection btw SuperKEKB and BelleII</u>

- Install optical cables to make direct connections.
- Install 10GbE switches for higher speed data transfer.

### 4. New network configuration

- Apply VLAN segmentation into the SuperKEKB control network.
- Change Network connections btw SuperKEKB control network and KEK laboratory network to enhance network security.

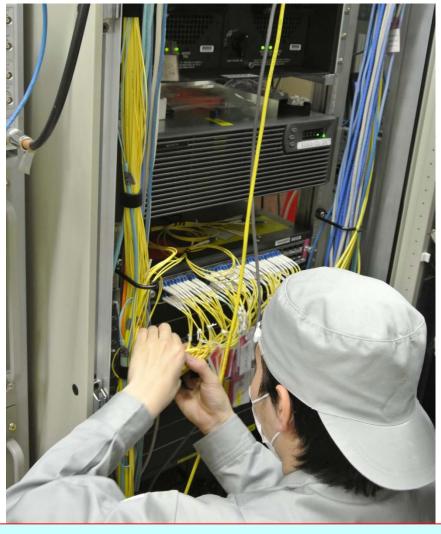
#### 5. Wireless LAN system installation

SuperKEKB tunnel, AR, sub-control rooms, power equip. buildings

## **10GbE Network Switch Installation**

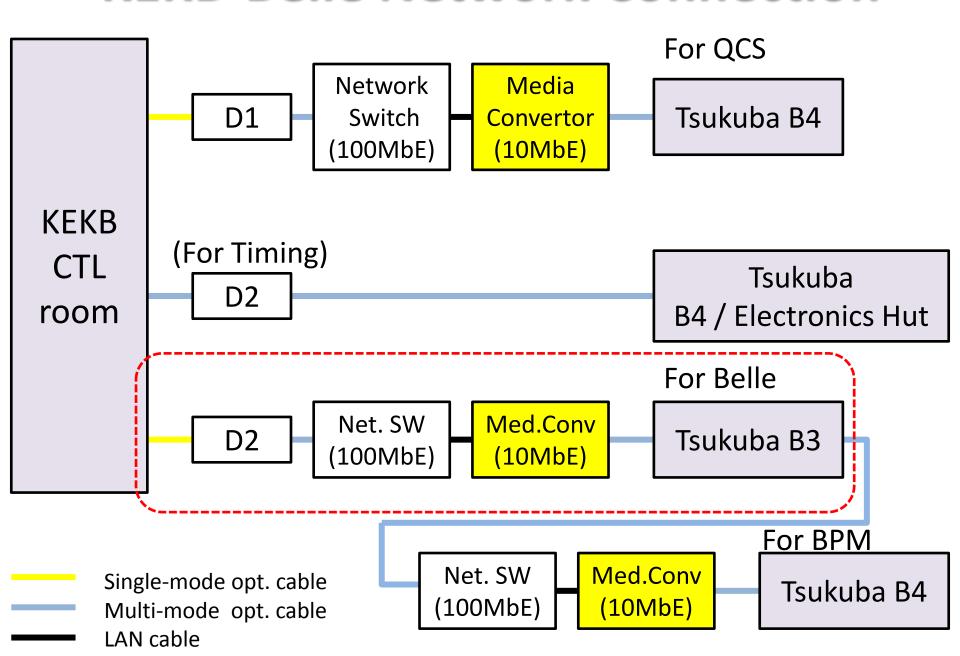




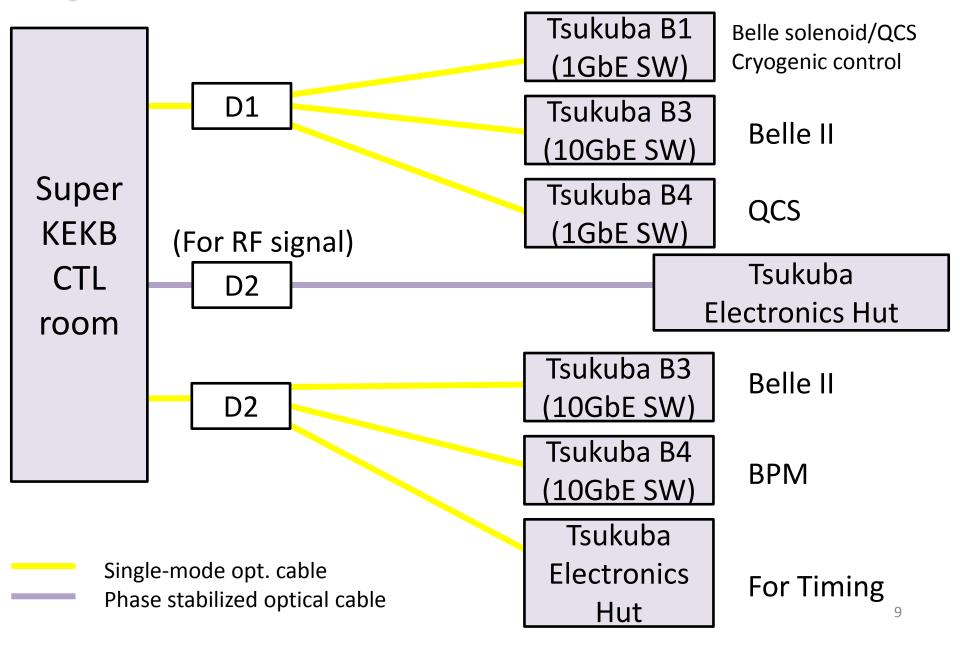


We install ~30 10GbE switches in Feb. 2014, and change the network configurations. (Redundant connections, VLAN segmentations)

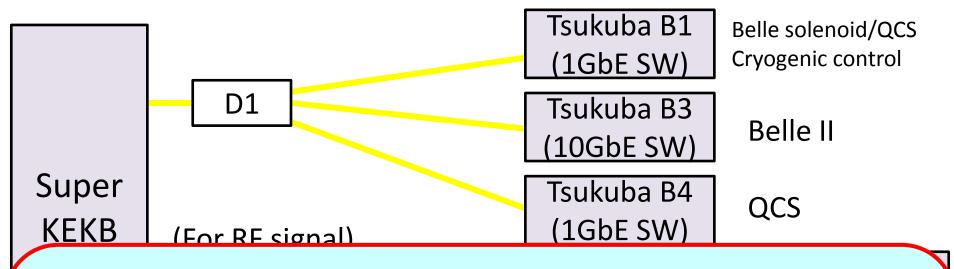
## **KEKB-Belle Network Connection**



# **SuperKEKB-Bellell Network Connection**



# **SuperKEKB-Bellell Network Connection**



- SuperKEKB & BelleII are directly connected
- Wider bandwidth data transfer (10MbE → 10GbE)

Optical cables are installed in Dec. 2013
Network switches are installed in Feb. 2014

## VLAN segmentation for SuperKEKB

- We use EPICS to control the accelerator.
- EPICS uses UDP broadcasts to communicate btw IOC & OPI.

Many UDP broadcast packets in the control network. (~90% of the total network traffic)

- More UDP broadcasts in the SuperKEKB network.

Accelerator components with Ethernet interface also receive the UDP broadcasts, and cannot work properly.

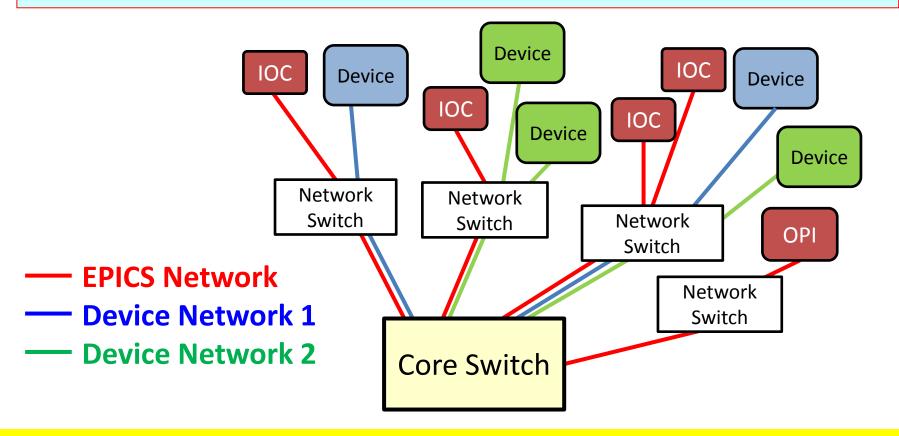
We apply VLAN segmentation to protect the accelerator components

SuperKEKB control network consists of

- 1. EPICS network (for EPICS IOC and OPI)
- 2. Device networks (for accelerator components)

# VLAN segmentation for SuperKEKB

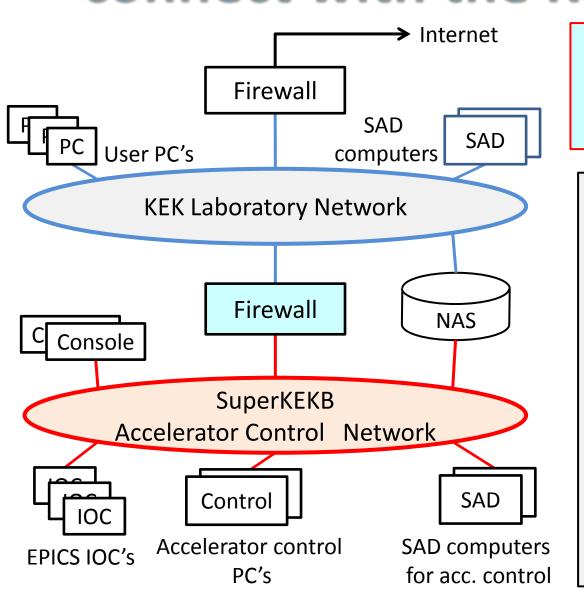
In Feb. 2014, we apply VLAN segmentation for the SuperKEKB control network.



#### We have tested the new VLAN segmentation

→ IOCs in the EPICS network can control the devices in the device network.

# Network reconfiguration to connect with the KEK network



We changed the network configuration in Aug. 2013.

→ Enhance the security

#### KEKB

Many computers connect to both KEK and KEKB control networks



#### <u>SuperKEKB</u>

Computers in acc. control network don't directly connect to the KEK network

# Wireless LAN system installation

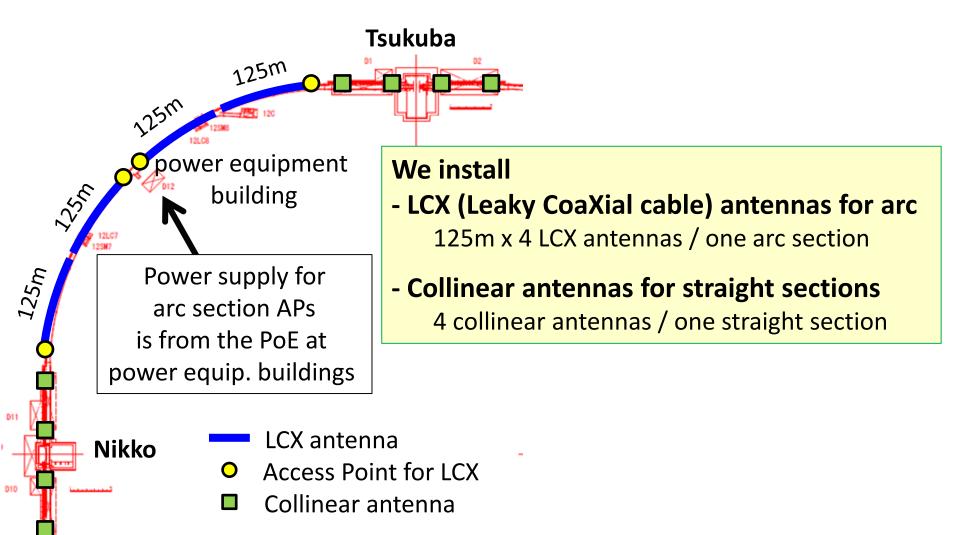
In JFY2012 – 2013, we installed wireless LAN into

- Whole SuperKEKB tunnel
- AR tunnel
- Power equip. buildings

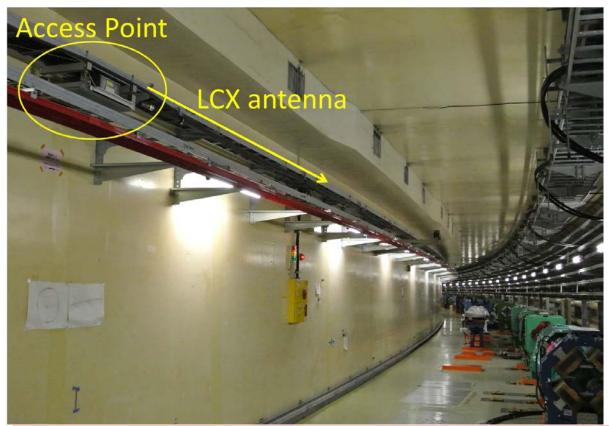
for construction and maintenance of the accelerator.

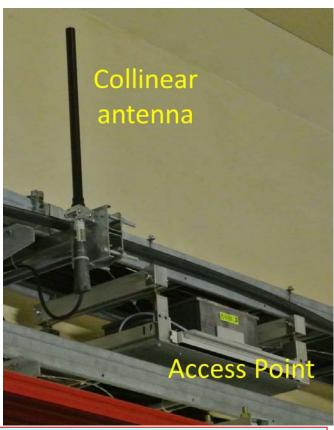
All access points (~70) as well as Linac's are controlled by 1 controller.

# Wireless LAN system into the whole 3km tunnel area



# LCX and Collinear antennas in the SuperKEKB tunnel





- Select LCX and Collinear antennas with radiation hardness >1MGy.
- APs and PoEs in the tunnel are installed within lead boxes.
- Connector connections are wrapped with lead sheets and fixed with polyetheretherketone (PEEK) cable ties.

# **Device Controller for SuperKEKB**

In KEKB, we mainly used VME/VxWoks IOC (I/O Contoroller) In SuperKEKB, we use

1) VME/VxWorks IOC CPU is upgraded

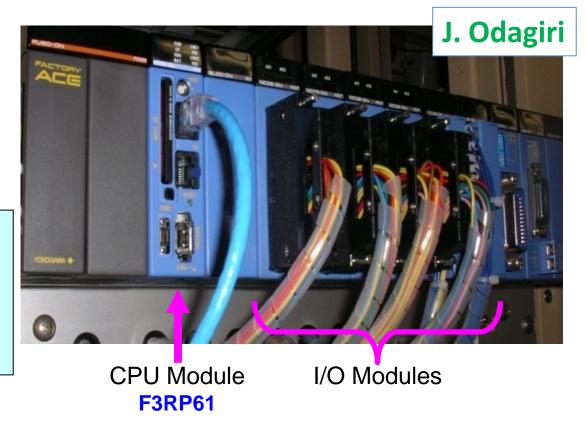
## 2) PLC/Linux IOC

- Yokogawa FAM3 series
- Linux running on the CPU module(F3RP61)

Apply for Vacuum system, Beam collimators, LLRF, Safety system, Magnet PS,

• • •

3) PC/Linux IOC



## Status of IOC Upgrade & Implementation

### Full Replacement in progress

```
    Vacuum Control
    VME IOC + CAMAC → PLC IOC
```

```
- LLRF Control VME IOC + CAMAC \rightarrow \muTCA IOC + PLC IOC
```

- Interface to PPS VME IOC  $\rightarrow$  PLC IOC

#### CPU Upgrade of VME IOC

```
Magnet PS in progress
```

BPM start soon

BT planning

#### VME IOC implementation

Beam Abort System in progress

### PLC IOC development & implementation

→ Next page

# Status of F3RP61 (PLC CPU module) Implementation

J. Odagiri

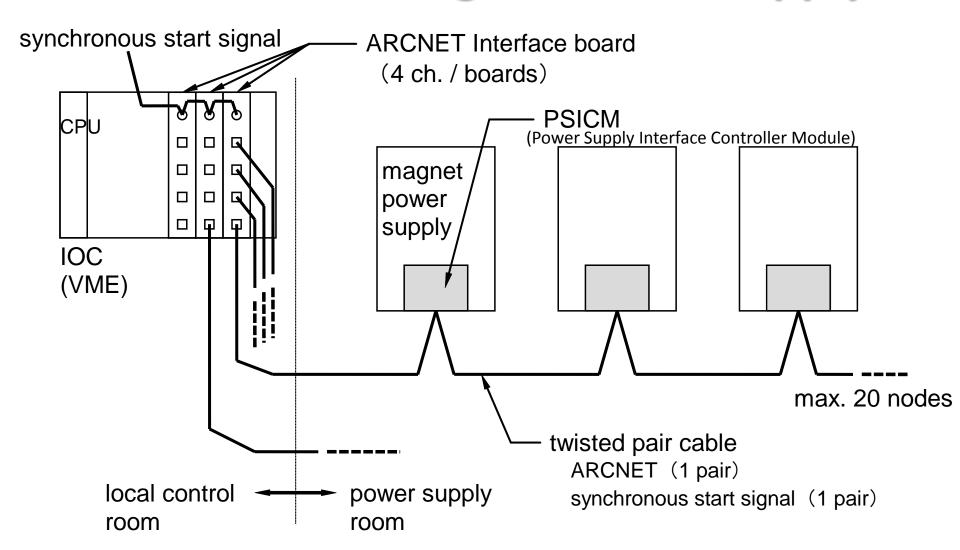
#### **FY2013**

- Interface to the Personnel Protection System
- LLRF (used with μTCA system)
- Vacuum system
- Current stability controller for the high current Magnet PS

### Things to do in FY2014

- Interlock system for the Magnet PS system
- Tilting Support (SX Magnet) Control
- BT
- Dumping Ring

## **ARCNET and Magnet Power Supply**



#### T. T. Nakamura, A. Akiyama

## Version up of the PSICM

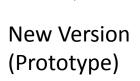
### (Power Supply Interface Controller Module)

- Interface/Controller card plugged in power supply
  - Microprocessor is embedded
  - ARCNET controller and driver
  - Timing signal input to start synchronous ramping

#### New version of PSICM

- Support high speed communication (10/5/2.5Mbps)
- Support high resolution Power Supply (24/20/18/16bits DAC)
- Fully compatible to the current version for the Magnet PS
- Redundant timing signals
- More reliable connectors







## **Magnet PS Control System**

- FY2013 Status
  - New PSICM
    - Development of the prototype ver.2
    - Final tuning of the firmware
    - First mass production (1000 pcs.)

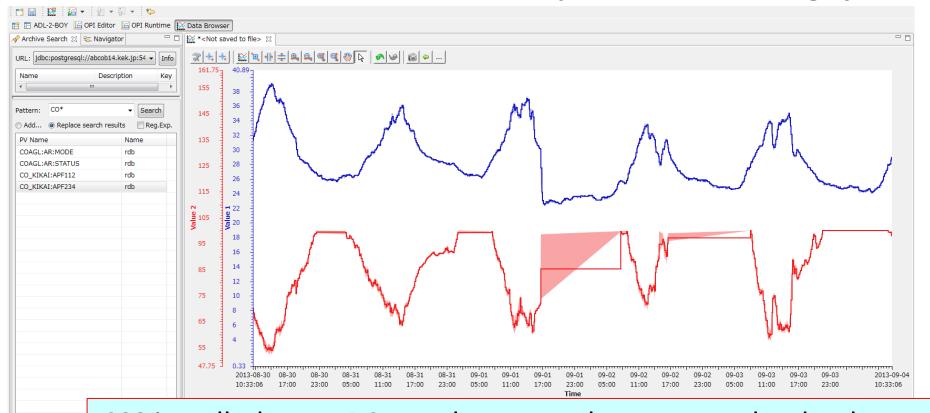
- $\rightarrow$  done
- $\rightarrow$  in progress
- $\rightarrow$  in progress

- FY2014 Plan
  - New PSICM
    - Second mass production (2000 pcs.)
      - → depends on budget
    - Installation
  - IOC/OPI Software development
    - modification from KEKB version

# **Data Archiving System**

- KEKBLog as a primary data archiving system (file based logging system)
- CSS(Control System Studio)-based Archiver + PostgreSQL

as the 2<sup>nd</sup> option data archiving system



CSS installed users PCs can be remotely access to the database For real-time / historical / trend monitoring

# **Data Archiving System**



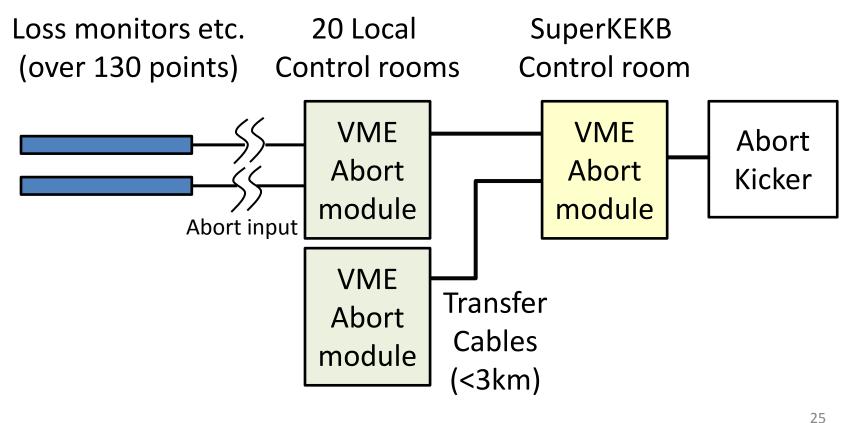
From October 2013, we monitor the QCS cryogenic system with the new archiving system (CSS + PostgreSQL).

→ Store ~300 points data every 5 seconds.

# **Beam Abort System**

T. Naito, A. Akiyama, S. Sasaki

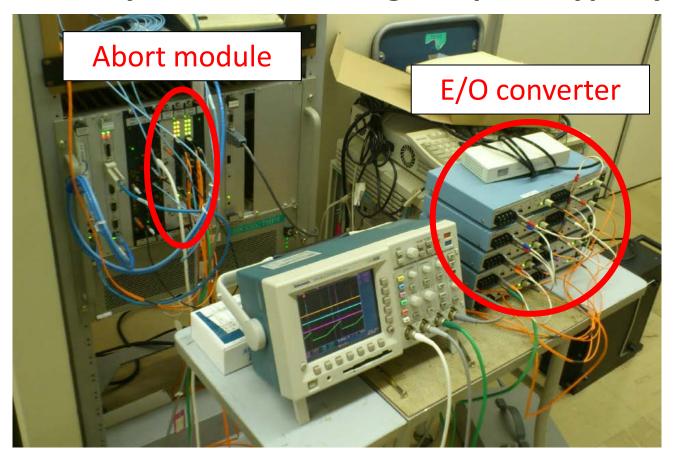
We have developed the faster response Beam Abort System for SuperKEKB E/O conversion, optical cable to transfer the signal, remove low-pass filters → Response time improved from 100µs to 20µs



# **Beam Abort System**

T. Naito, A. Akiyama, S. Sasaki

- JFY2013 System check using the prototype system.



- JFY2014 Installation of the new beam abort system.

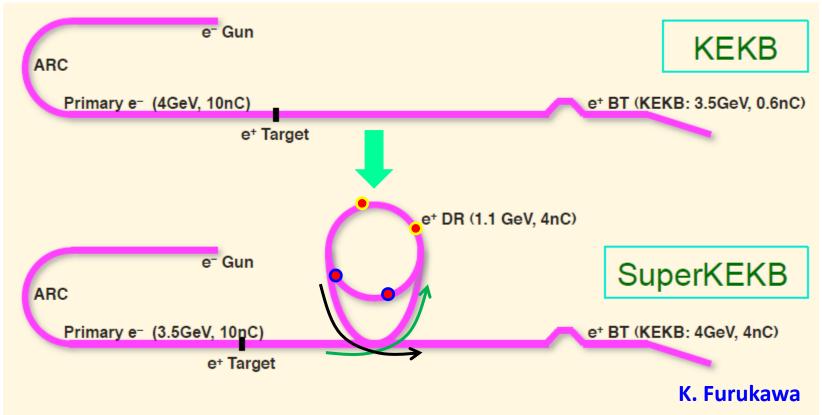
## **Timing System for positron injection**

H. Kaji, K.Furukawa (Details in the Kaji-san's talk)

In SuperKEKB, we construct the positron Damping Ring

→ Positron injection timing scheme become complicated

To account for DR, new timing system for e<sup>+</sup> injection is required



# Wire Scanner System

Wire scanners are used as beam profile monitors at Linac and BT.

#### **Control System is upgraded**

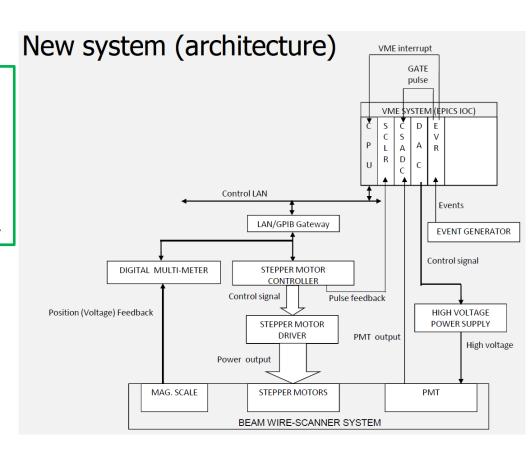
1. CAMAC retired.

#### 2. Event Receiver is installed.

- It enables the multi-beam operations.
- The 1<sup>st</sup> IOC using the new version of FPGA and firmware
  - ⇒ This experience is helpful for upgrade of the Main Trigger Station.

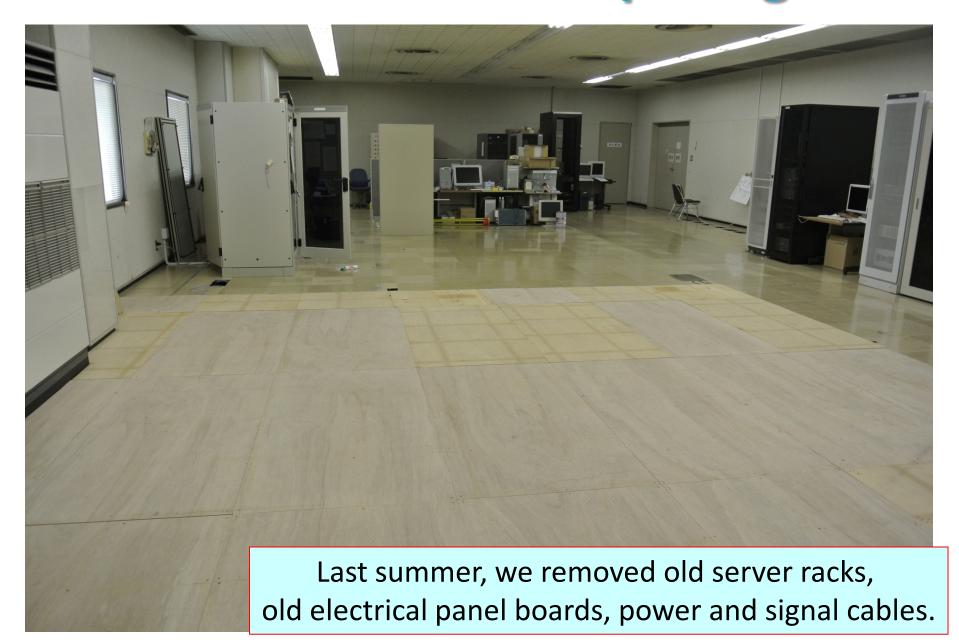
#### 3. New functions are integrated

- Change wire speed during the scan.
- Capability for multi-mode operation
- Synchronization with BPM on-going
  - ⇒ for collection of beam position and current, pulse-by-pulse.



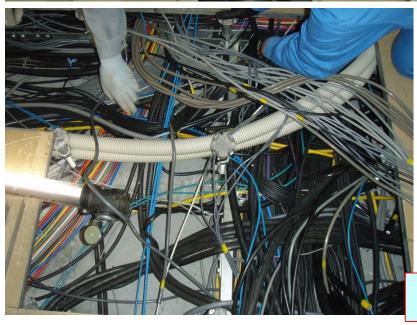
Three systems have already installed and two of them are operated. Installations of a few more wire scanners are planned.













We removed old cables (3t in total).

Electrical panel boards are renewed





# Summary

# Upgrade of the accelerator control system for SuperKEKB is in progress

## In JFY2013, we did

- New network system construction
- Device controller upgrade & implementation
- Additional new data archiver construction
- Beam abort system R&D
- Timing system R&D
- Renovation of the computing room

# Summary

## In JFY2014, we should do

- Network system for damping ring
- New computing server system
- Device controller upgrade & implementation
- Beam abort system installation
- Timing system upgrade
- Renovation of the control room console system
- Accelerator operation equipment

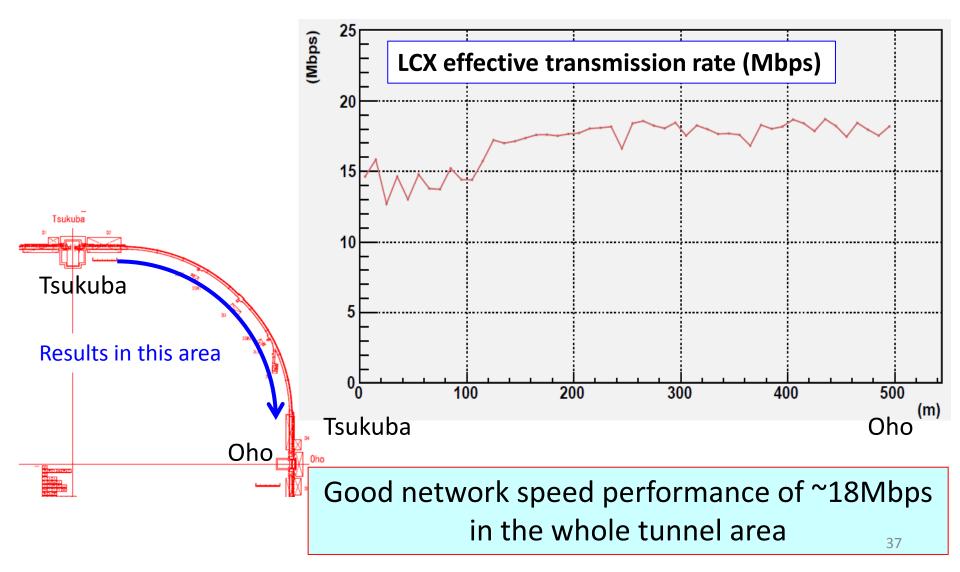
  New alarm system, task launcher, operation panels, ...

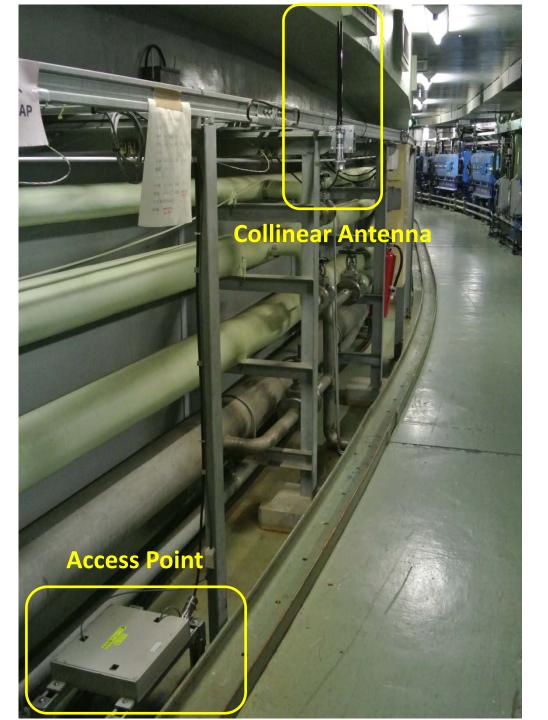
## for the 1<sup>st</sup> SuperKEKB operation in 2015.

# Backup slides

## Wireless LAN in the SuperKEKB tunnel

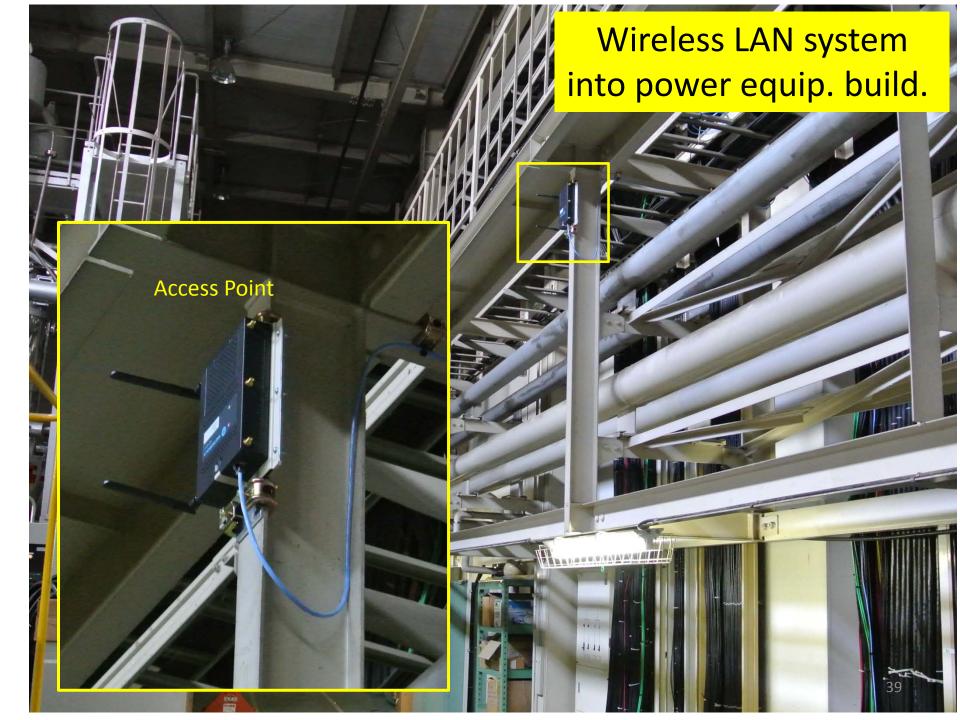
We measured the wireless LAN network speed in the SuperKEKB tunnel.





## Wireless LAN system Installation into AR







## **EPICS on PLC**

- VxWorks CPU was available on PLC (Yokogawa, Mitsubishi)
  - □ Besides normal sequence / ladder CPU
- ◆Yokogawa starts to provide Linux (2.6) on PLC CPU (F3RP61)
  - Brave enough to choose open source environment
    - **™** We negotiate with Yokogawa to remove any license issues
  - \*Odagiri/KEK, Uchiyama/SHI-RIKEN, Yamada/KEK made much effort to realize EPICS implementation, (but no need for asynchronous records)
- ◆ Four F3RP61-based IOCs are used in KEKB operation
  - ❖Three since September 2008, and another later, four in total
  - Beam mask controllers and Pulsed-quad controllers
  - ❖No trouble at all, they run more than 8 months
- ◆~20 new IOCs are also used in J-PARC operation now



## F3RP61 (e-RT3 2.0)

Linux 2.6.24 PPC 533MHz 128Mbyte RAM

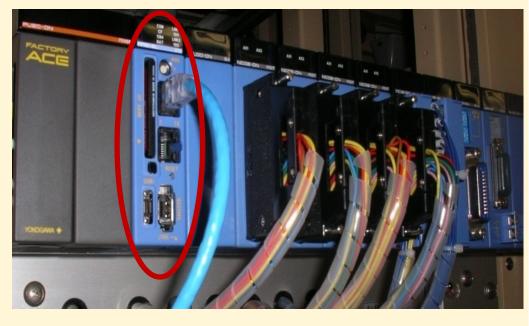
100BaseTx x2

**USB** 

**IEEE1394** 

Serial

PCI



KEKB Beam mask controller

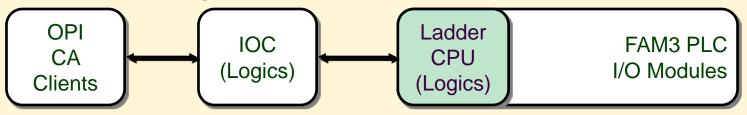
I/O Bus for FAM3 Module Interface
can access to mature FAM3 I/O Modules
Can be combined with conventional ladder CPU
Software development environment (ELDK)



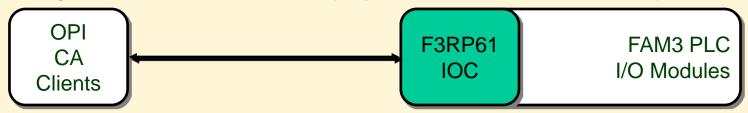


## Simple Usage under EPICS

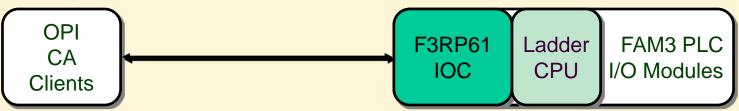
Conventional PLC usage with asynchronous access



PLC usage with F3RP61 with only synchronous access and maybe with sequencer



If necessary, we can combine



## Number Of F3RP61-based IOC

Group	Expected numbers (at T = 0)
RF (including LLRF)	13 + 2
Vacuum	14
Magnet/Magnet Power Supplies	11 + 3
Personnel Protection System	8
Beam Monitor	1 + (?)
BT	2+(?)
Dumping Ring	?
Helium Refrigerator	1
Total	>39+(?)