#### Main Ring Magnet system

Mika Masuzawa

Magnets:
Magnet design &
Field measurements
Installation
Survey & alignment

Power supply design
Testing
Tuning
Installation
Cabling
Check

T. Oki's talk

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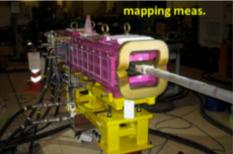
1. Introduction of the MR magnet upgrade



#### SuperKEKB Upgrade

Completely new beam lines around the IP "Tsukuba straight section"

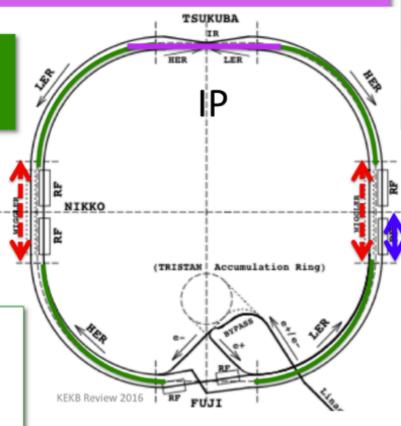




New longer dipole magnets in the LER (~100)

New: added 280 wigglers to the LER

New vertical steering magnets (~220). Modification of horizontal steering magnets (~300)

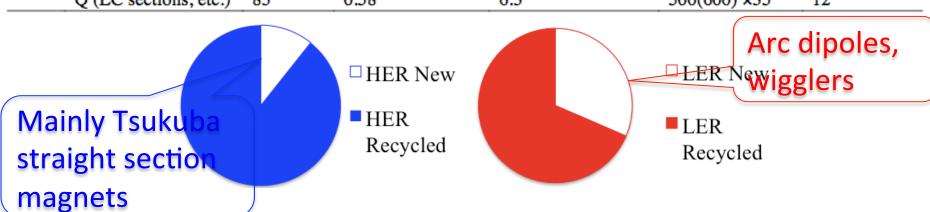


36 wigglers added the HER.



# Parameters of the newly fabricated MR main water-cooled magnets

Ring	Magnet (main locations)	g/2 (mm)	Leff (m)	Max. B, B', B'' (T),(T/m),(T/m <sup>2</sup> )	I(A) × # turns/pole	# of magnets (Phase I)
HER	B (LC section)	55	3.96	0.3	1325×10	11
	B (IR)	55	3.60/2.23	0.112	500×10	1/1
	Q (LC sections, etc.)	50	1.12/0.57	18.0	700×26	2/33
	Q (Arc sections)	50	0.82	12.8	500×26	8
	Q (IR)	55	0.53	2.0	500×6	2
	Sx (LC sections)	56	0.608/0.509/0.335	472/465/447	600×22	4/4/2
LER	B (Arc sections, etc.)	55	4.19	0.19	840×10	114
	B (LC sections)	55	3.96	0.3	1325×10	5
	B (IR)	55	2.2/1.6	0.223	1000×10	2/1
	Wiggler	55	0.34/0.22	1.18/0.76	1400×36	56/112
	Q (LC sections, etc.)	83	0.58	6.3	500(600) ×35	12



+ ~250 steering magnets

2. Things needed to be done for the MR start-up

#### Things needed to be done for the MR start-up

#### Magnet installation

In the north tunnel.

#### Survey and alignment

•2<sup>nd</sup> round survey of the entire tunnel followed by final alignment of the magnets.

Magnetic field measurements (to evaluate the magnetic coupling between adjacent magnets)

#### Cooling water

- •Water flow check and balancing among 2000 magnets Power supply system (T. Oki's presentation)
  - •Full-scale start-up and tuning of the power supplies.
  - Cabling checks, including polarity.

#### Completion of the database

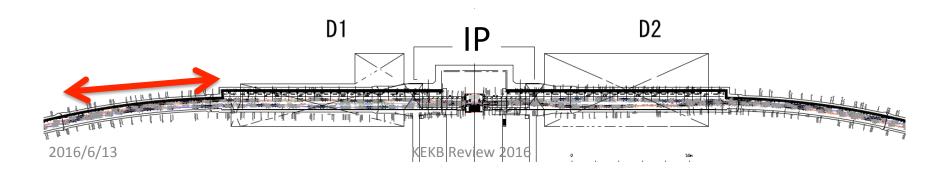
→ Integration of all this in time was needed.

## Magnet installation

NORTH TUNNEL
DITHER COILS (PHASE II)

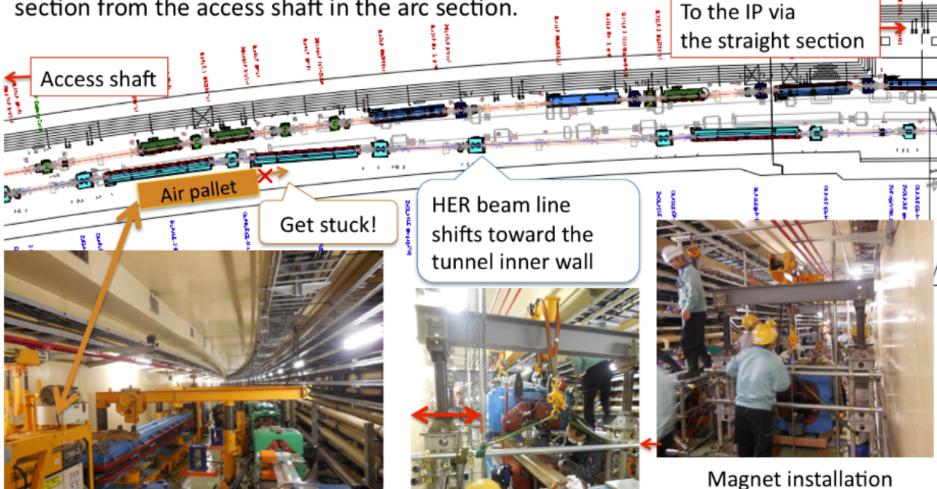
# Magnet installation in the north tunnel

We needed to wait until the vacuum chambers were ready to be installed.



#### North tunnel

Once the magnets are installed here, the air pallet can no longer be used to transport anything to the straight section from the access shaft in the arc section.

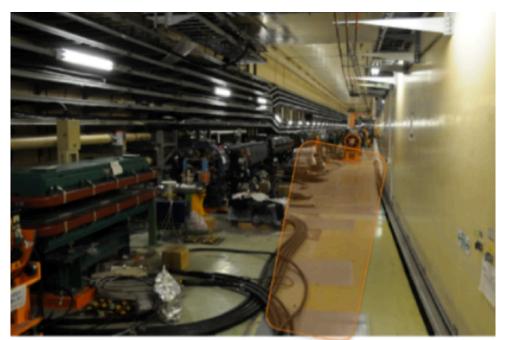


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Vacuum chamber installation

with a chain-block

on a support frame.



North tunnel Magnet installation completed In May 2015.



Replacement of a vacuum pipe in a quadrupole magnet would be a nightmare.

Because the air pallet can not go beyond this point and We need to build a support frame from which to suspend the chain-block to open the quads.

#### Installation of the dither coils

The dithering coils were designed, fabricated, and field measured by SLAC, and shipped to KEK in April, 2015



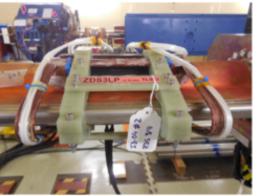
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#### Installation

Installation and checks completed in June, 2015. Many many thanks to Uli and the SLAC team.









Power supplies, cabling done.



System not completed.

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# Survey and alignment

Survey Results,
Strategy for the final alignment
Tunnel motion monitoring

## 2<sup>nd</sup> round survey campaign

June and July 2015

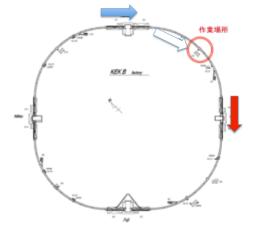


Survey was carried out by 3 teams. Calibration of the laser trackers was done carefully.

Special attention was paid to systematic errors, as even very small systematic errors can result in a large error at the end over hundreds of measurement sets.

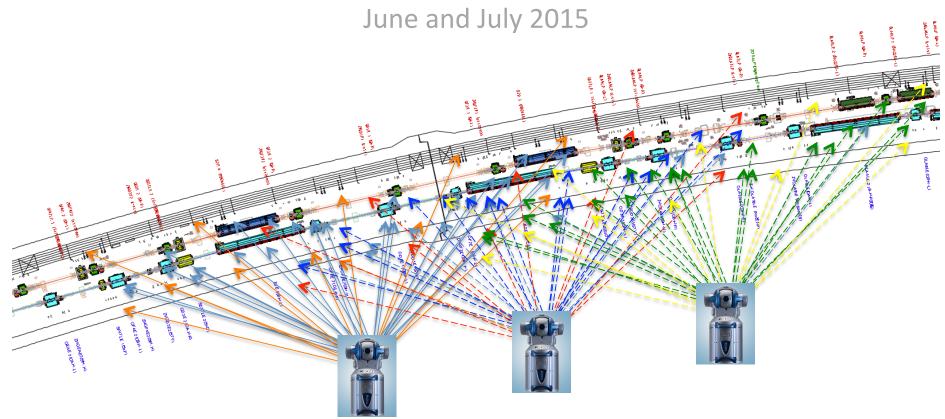


(long) distance being compared with TS30



**(EKB** eview 2016)

## 2<sup>nd</sup> round survey campaign



#### Constraints on the working area/time

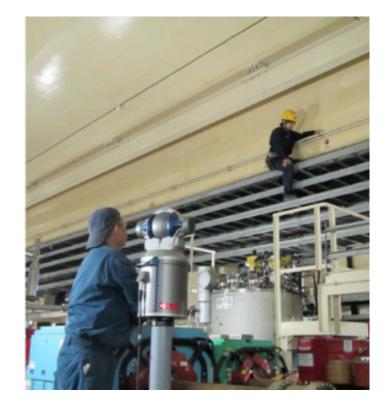
Alignment can not coexist with PS test, PS test can not coexist with water flow check, none can coexist with RF high power test (if in the same area)...,civil engineering can not coexist with survey/alignment...

More than 1200 network control points in the tunnel More than 4000 reference points for the magnets More than 5000 points to be surveyed and analyzed.

More than 400 LT settings, with overlaps

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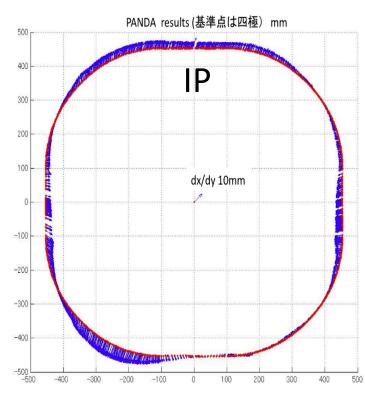




## Survey Results

#### IN THE HORIZONTAL PLANE (X,Y)

We got hundreds of data points every day from 3 teams, which were analyzed and cross-checked by T. Adachi, T. Kawamoto & M.Masuzawa independently everyday. If we found something funny, we requested the survey team to go back before they moved a long distance down the tunnel.



The north and west parts expands to the outside as large as 10 mm. This probably happened when the TRISTAN monuments were first built.

Does this matter?

→ No. Deformation of low order does not matter.

#### **Constraints:**

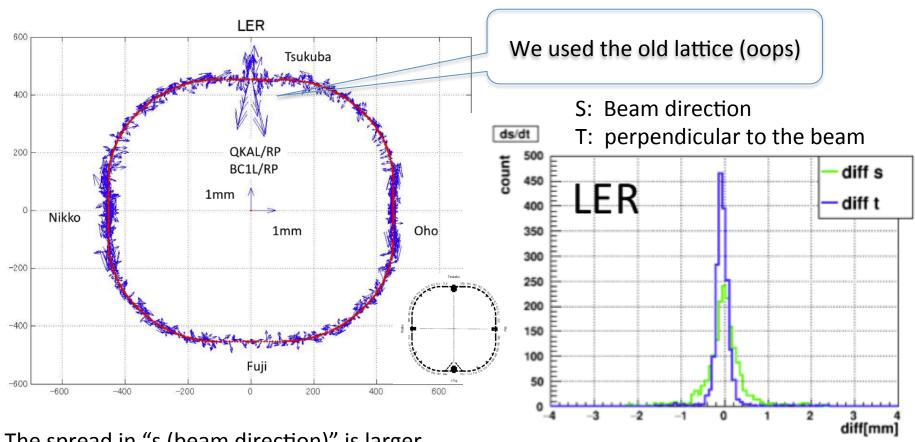
The rings have to close.

→ Smooth periodic curves will do.

Our choice was Fourier series (n=60). We tried FS with n=30 but the # of magnets to be adjusted increased, the amount of the adjustment became larger...

(of course we can do it but it would have affected other accelerator components such as vacuum chamber and rf...)

Deviation from smooth curves (we call it the "Adachi Curve")



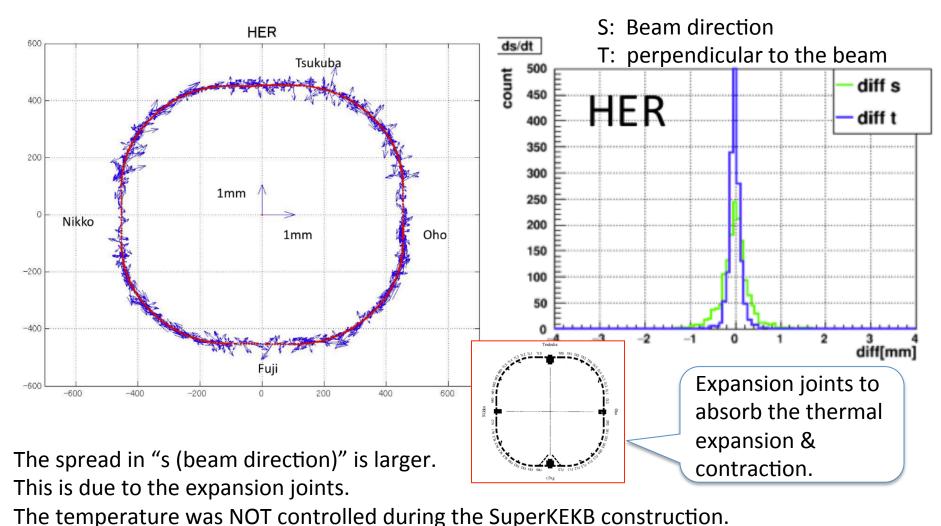
The spread in "s (beam direction)" is larger.

This is due to the expansion joints.

The temperature was NOT controlled during the SuperKEKB construction.

The temp. differ between when we did the 1<sup>st</sup> rough alignment and the 2<sup>nd</sup> survey.

Deviation from smooth curves (we call it the "Adachi Curve")



The temp. differs between when we did the 1<sup>st</sup> rough alignment and the 2<sup>nd</sup> survey.

## Alignment strategy

Discussion with the optics group

Time (schedule), man power (cost), impact to the other groups, against machine performance (good enough for Phase I) was discussed with the Optics G.

	Tolerance (Δt)	Tolerance (Δs)
Dipole	0.4mm	0.8mm
Wiggler	0.4mm	0.8mm
Quadrupole	0.2mm	0.4mm
Sextupole	0.2mm	0.4mm
LER Dipole(3 ref. pts)	0.4mm 0.8mm	

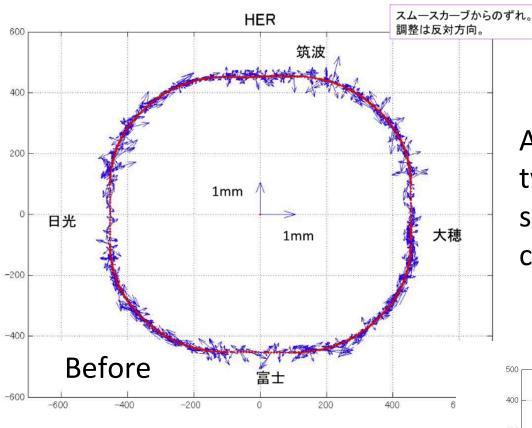








Obviously not here.

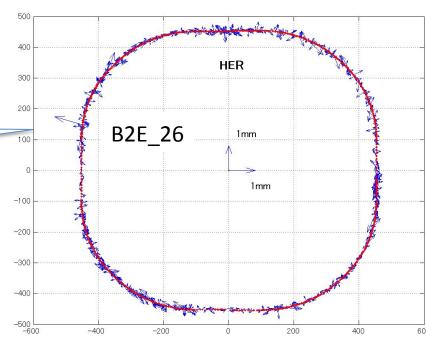


#### Alignment strategy

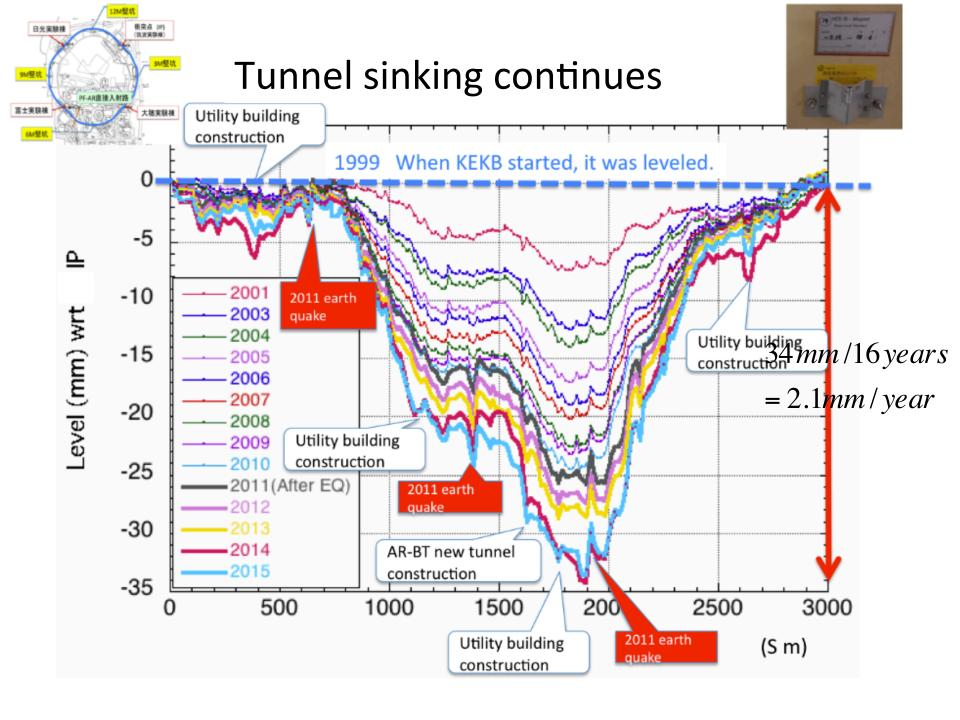
Alignment was carried out by two teams, followed by a survey team dedicated to checking the alignment.

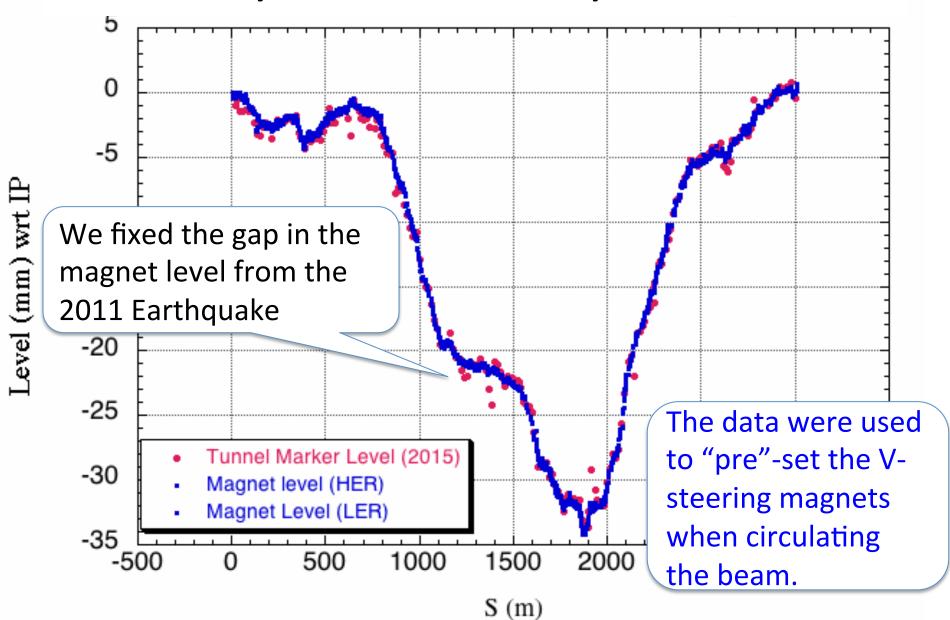
Found a misalignment, which was fixed right away.

安心して下さい



# Survey Results VERTICAL (LEVEL)

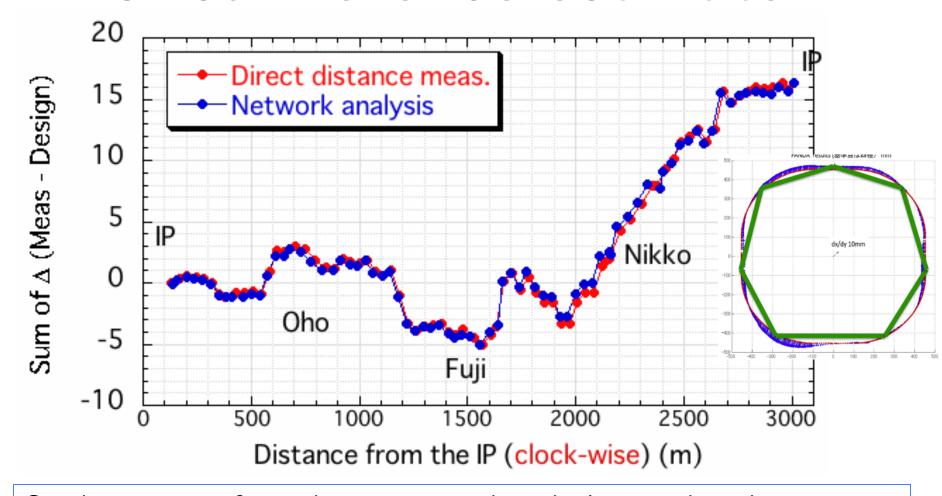




### Survey Results

CIRCUMFERENCE PREDICTION FOR A SMOOTH START UP OF THE BEAM CIRCULATION

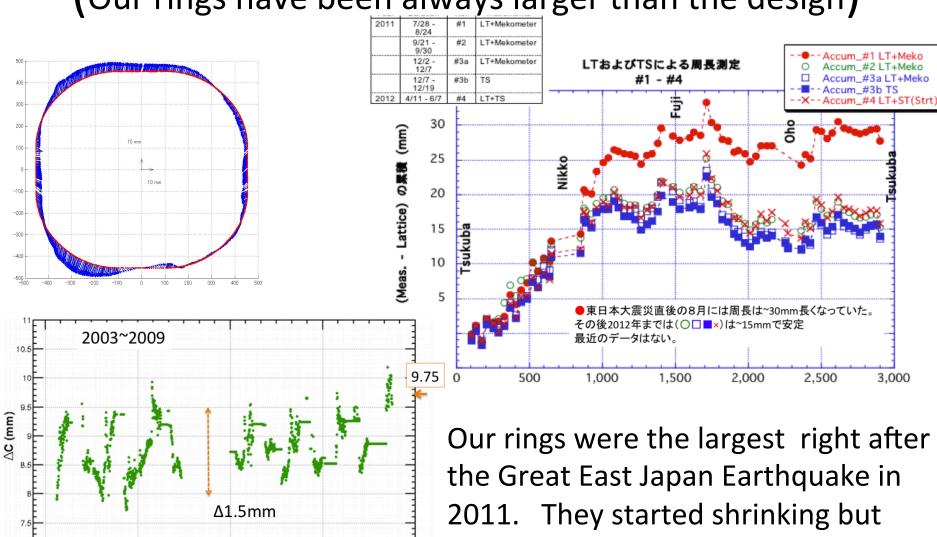
#### Circumference estimate



Our best guess from the survey and analysis was that the circumference is about 16.4 mm longer than the SuperKEKB design. This information was used when injecting the LER beam to the ring on Feb.9, 2016 and the beam said Yes!

#### Our rings look like this

(Our rings have been always larger than the design)



12/31/2004

12/31/2006

Date

12/31/2008

not back to the level of KEKB.

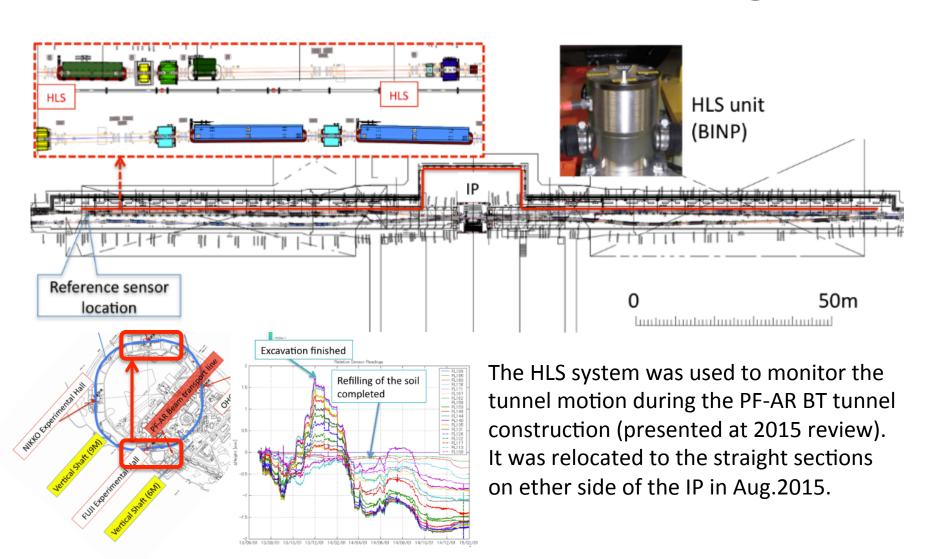


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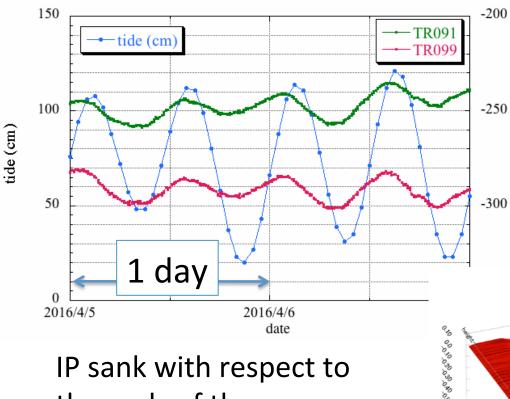
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# Tunnel Motion Monitoring HLS (HYDROSTATIC LEVELING SENSORS)

### Tunnel motion monitoring



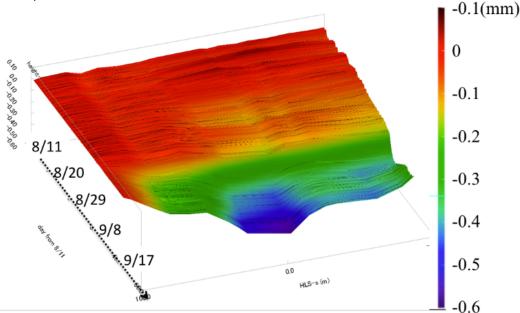
### Tunnel motion monitoring



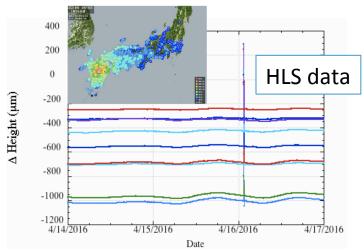
A clear tidal (vertical) motion is seen around the IP.

The amplitude is  $\sim 20 \mu m$  (P-P) during this period.

IP sank with respect to the ends of the straight sections by ~0.6mm due to heavy rainfall in the area.



#### Tunnel motion monitoring

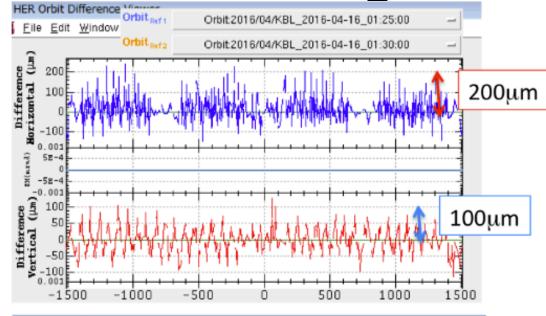


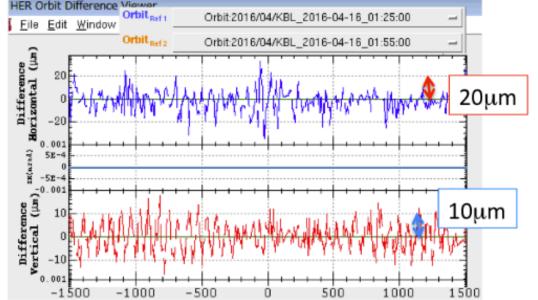
The 2016 Kumamoto earthquake (magnitude 7.3) hit Kumamoto. It took ~ 4 minutes for the seismic wave

to arrive at the SuperKEKB ring.

It disturbed the accelerator components but the abort system for the circulating beams was not triggered.

Orbit difference
During the EQ – before EQ (top)
After the EQ – before EQ (bottom)





#### We came a long way



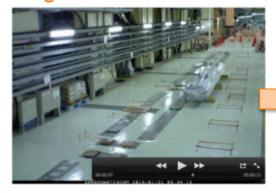


Dismantling of the KEKB magnet



2011 Earthquake

Magnets cables removed



SuperKEKB Beam line



Magnets being installed



SuperKEKB layout







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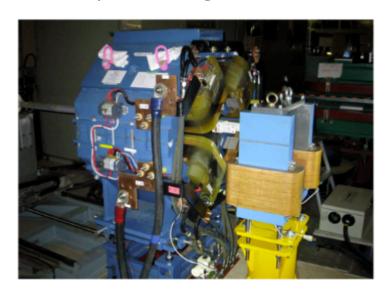
A big milestone for us 2/9/2016

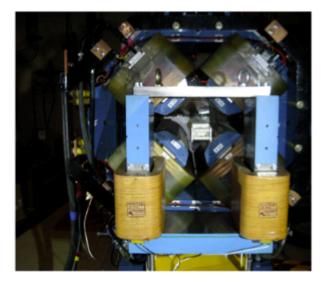
# Magnetic field measurements

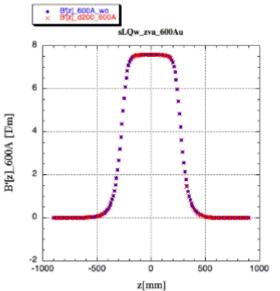
coupling between adjacent magnets

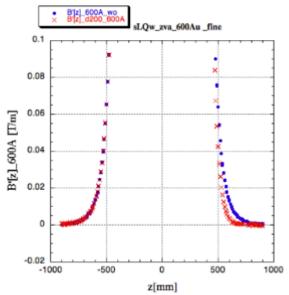
2016/6/13

# Magnetic coupling between adjacent steering magnet and Quadrupole magnet was evaluated & measured by K. Egawa

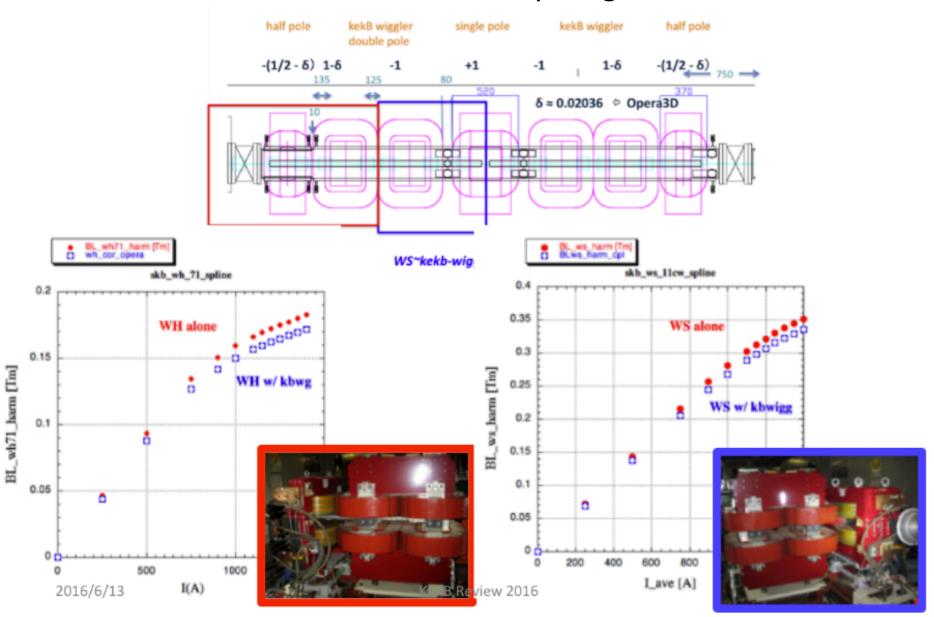








# Magnetic coupling between adjacent wigglers was evaluated & measured by K. Egawa



#### 3. For Phase II

Preparation for New IR, Installation & alignment of the QCS magnet system, design and fabrication of the collision FB ("iBump") magnets, building the dithering system, and so on.

Survey of the rings after a long shut-down and before Phase II.

Alignment of the ring magnets, if needed.

#### Summary

- The SuperKEKB MR magnet system was completed in time for Phase I commissioning.
- •The prediction for the circumference agreed with the actual circumference within 1 ppm accuracy and the difference in the circumference in both rings was found to be a couple of hundred microns, which contributed to a smooth start-up of the MR.
- •We would like to add more (BINP) HLS sensors to monitor the tunnel level change, especially at the IP & LCC sections.
- The power supply system is up and running smoothly with very high stability → T. Oki's talk.

2016/6/13

#### Summary

- We will investigate any problems found by beam commissioning:
  - Misalignment if any,
  - Improvement in the magnet data
    - •Magnetic coupling of wigglers, near-by magnets, for example.
- •We are preparing for the installation of the QCS system, which will take place in the summer, 2016.
  - •We have started to work closely with the QCS group on the alignment of the Single Stretched Wire (SSW) system which affects the cryostat alignment to the beam line.

